

Design of Multi-Model Linear Inferential Sensors with SVM-based Switching Logic

Martin Mojto¹, Karol Ľubušký², Miroslav Fikar¹ and Radoslav Paulen¹



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in Bratislava, Slovakia

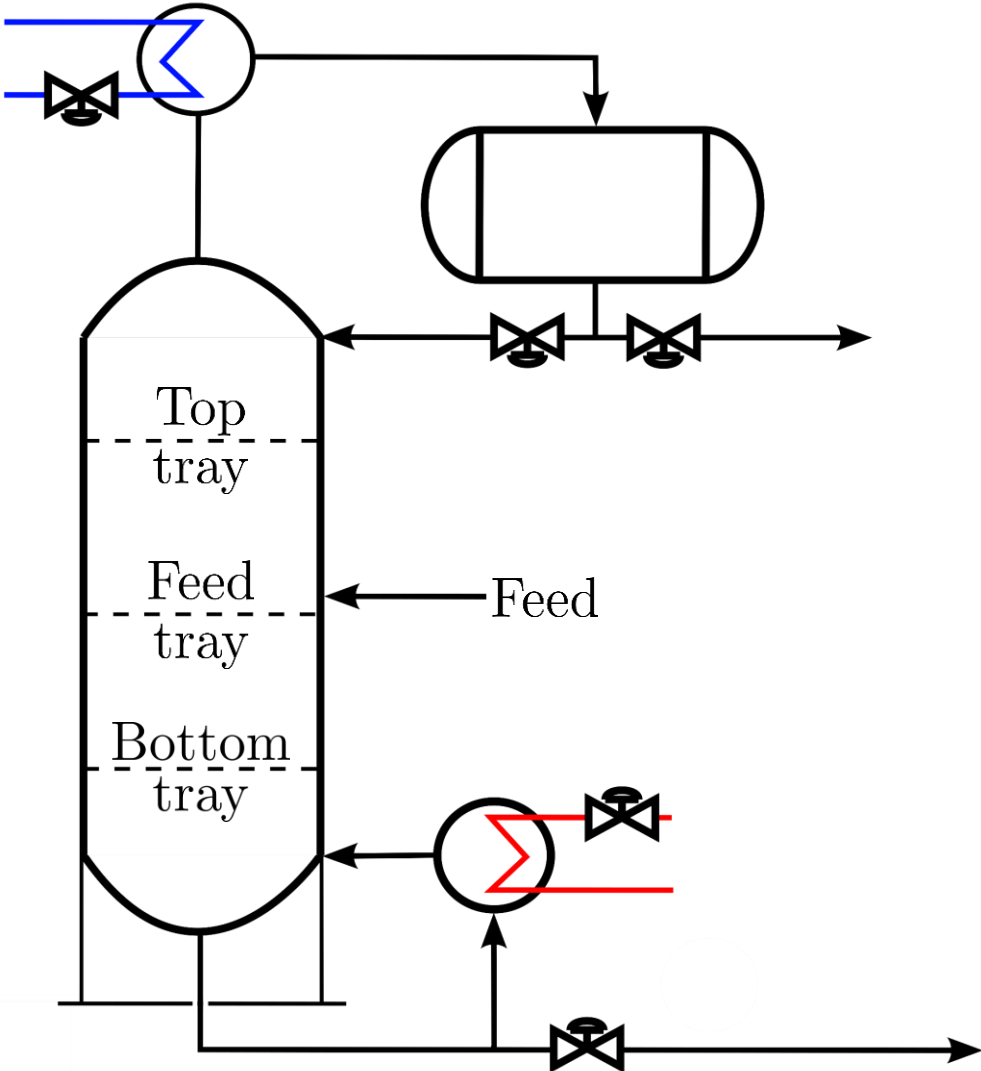
²Slovnaft, a.s., Bratislava,
Slovakia



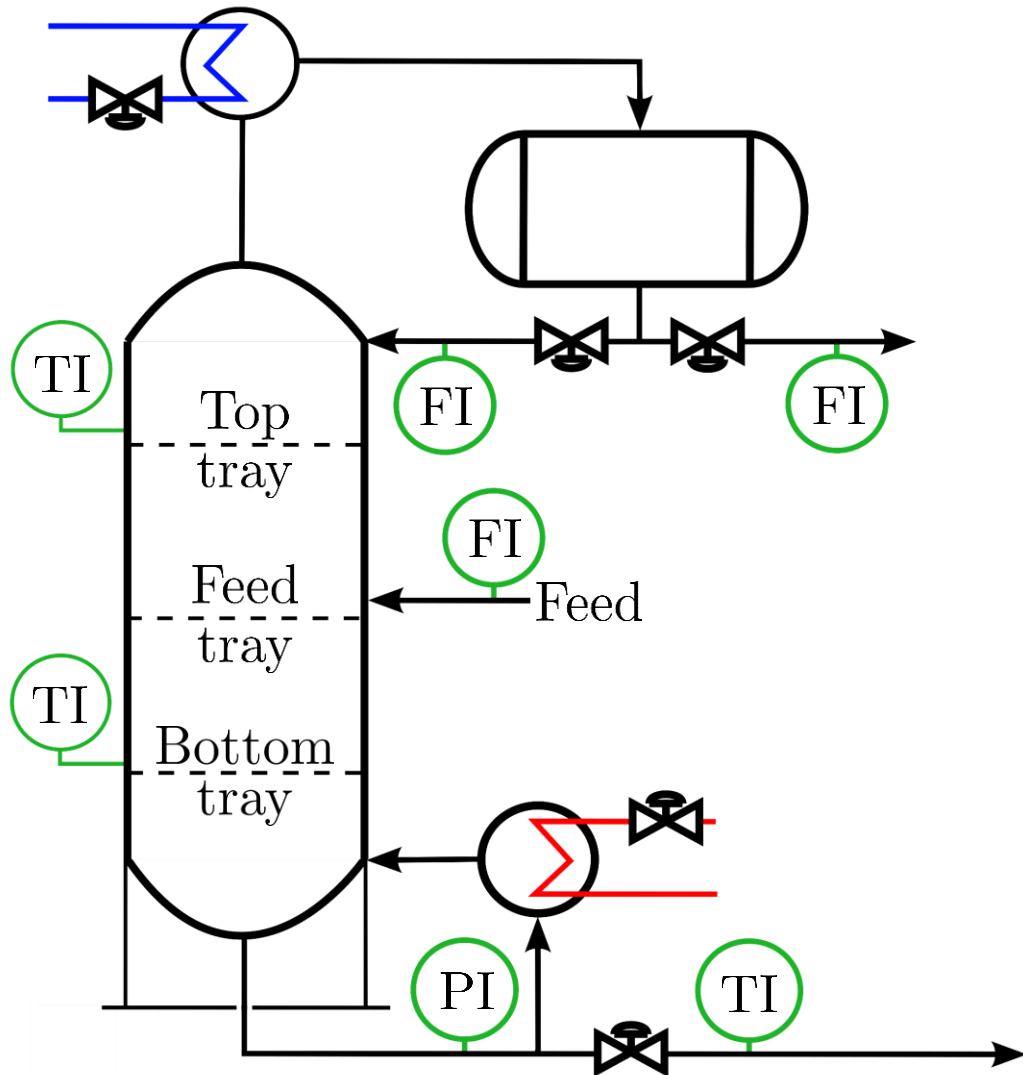
IFAC World Congress
July 9–14, 2023



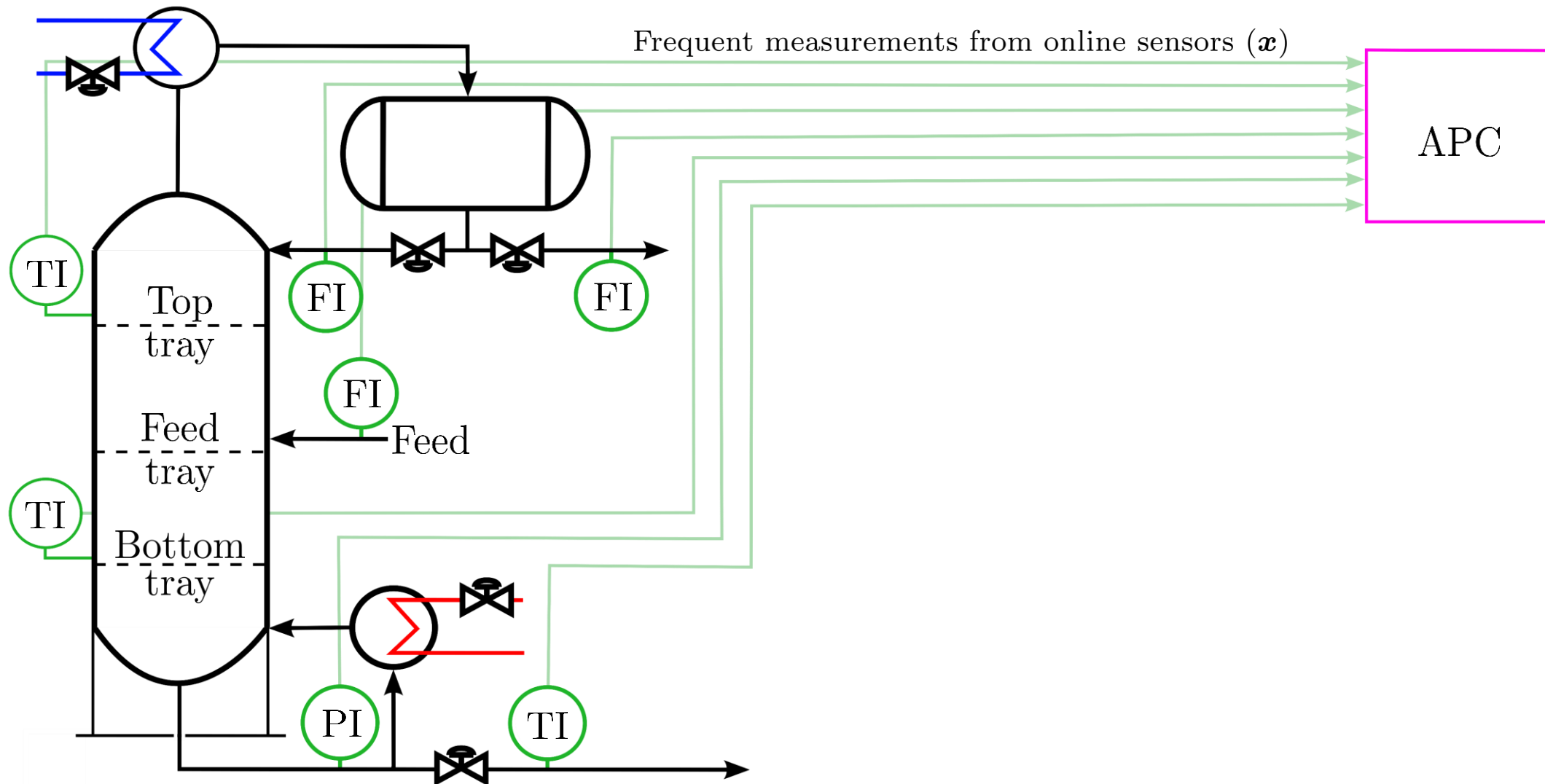
Motivation: Inferential Sensors



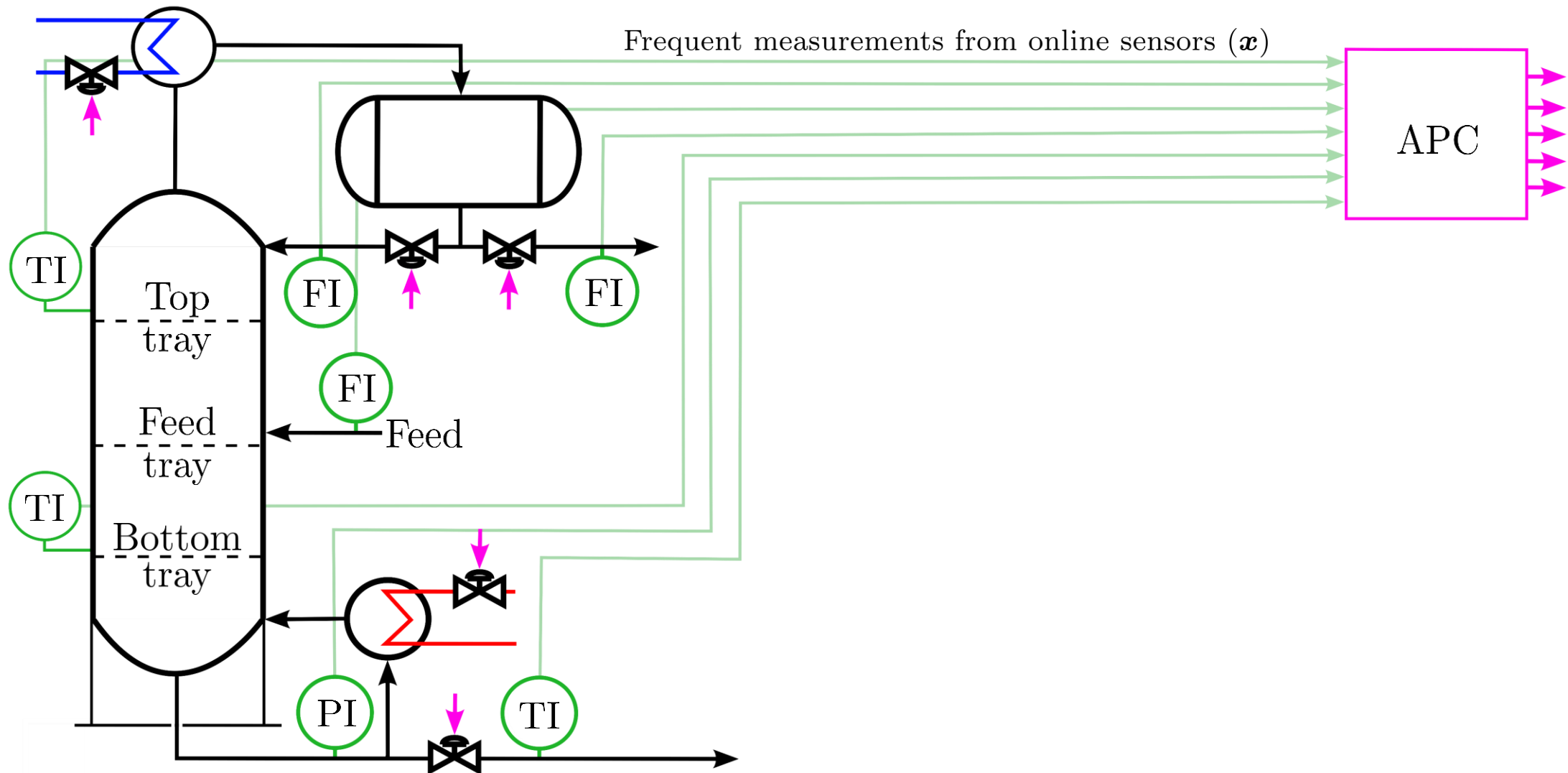
Motivation: Inferential Sensors



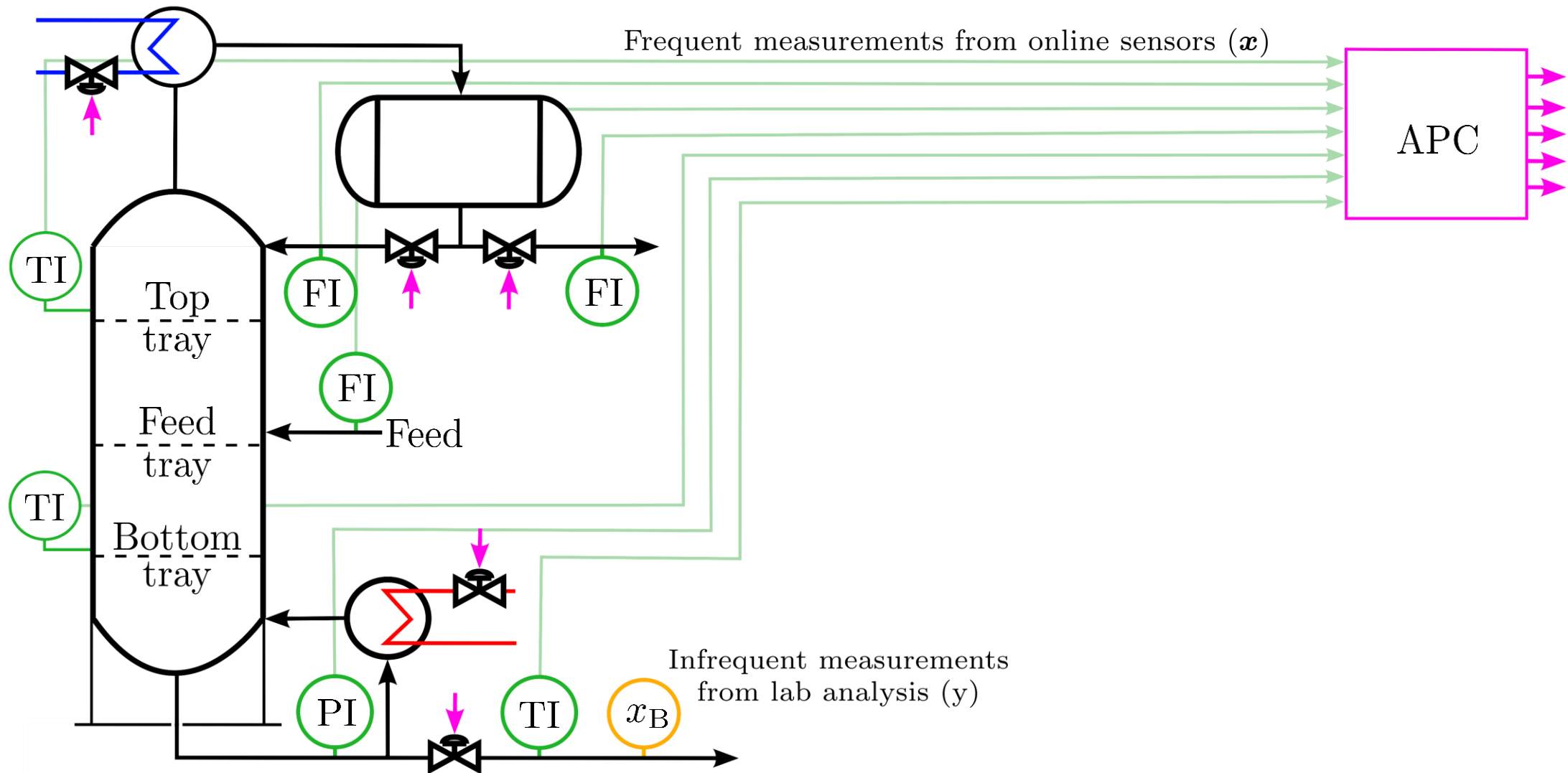
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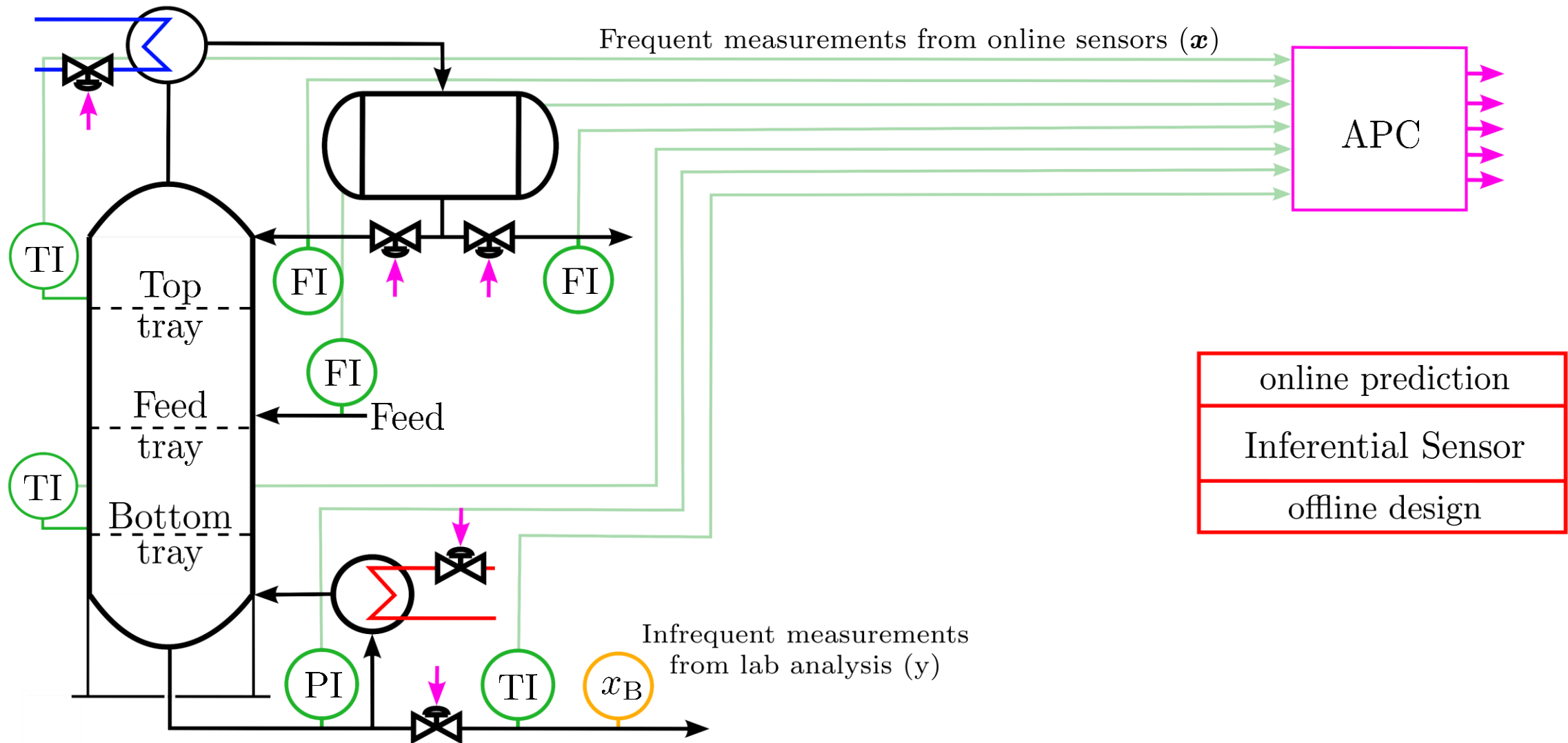
Motivation: Inferential Sensors



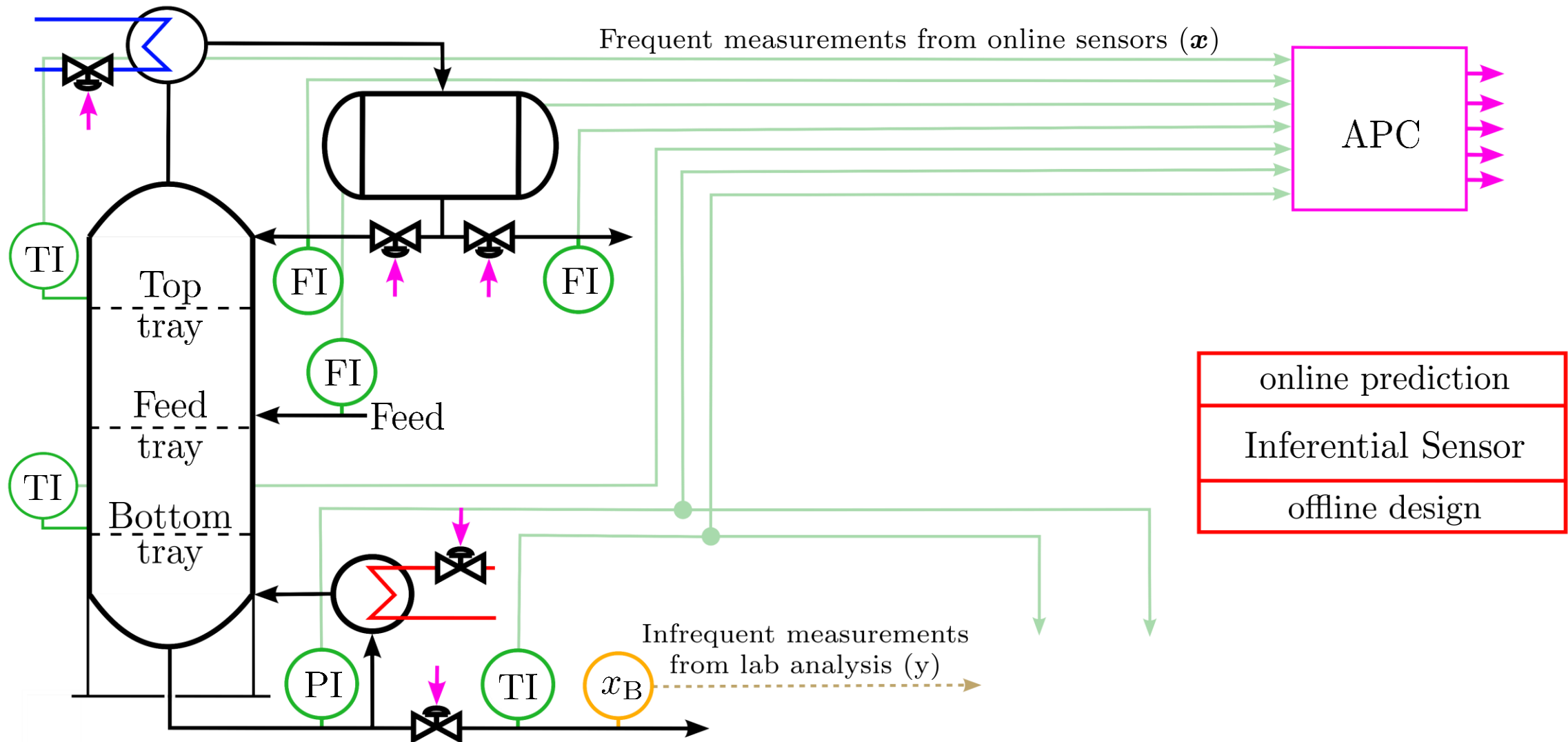
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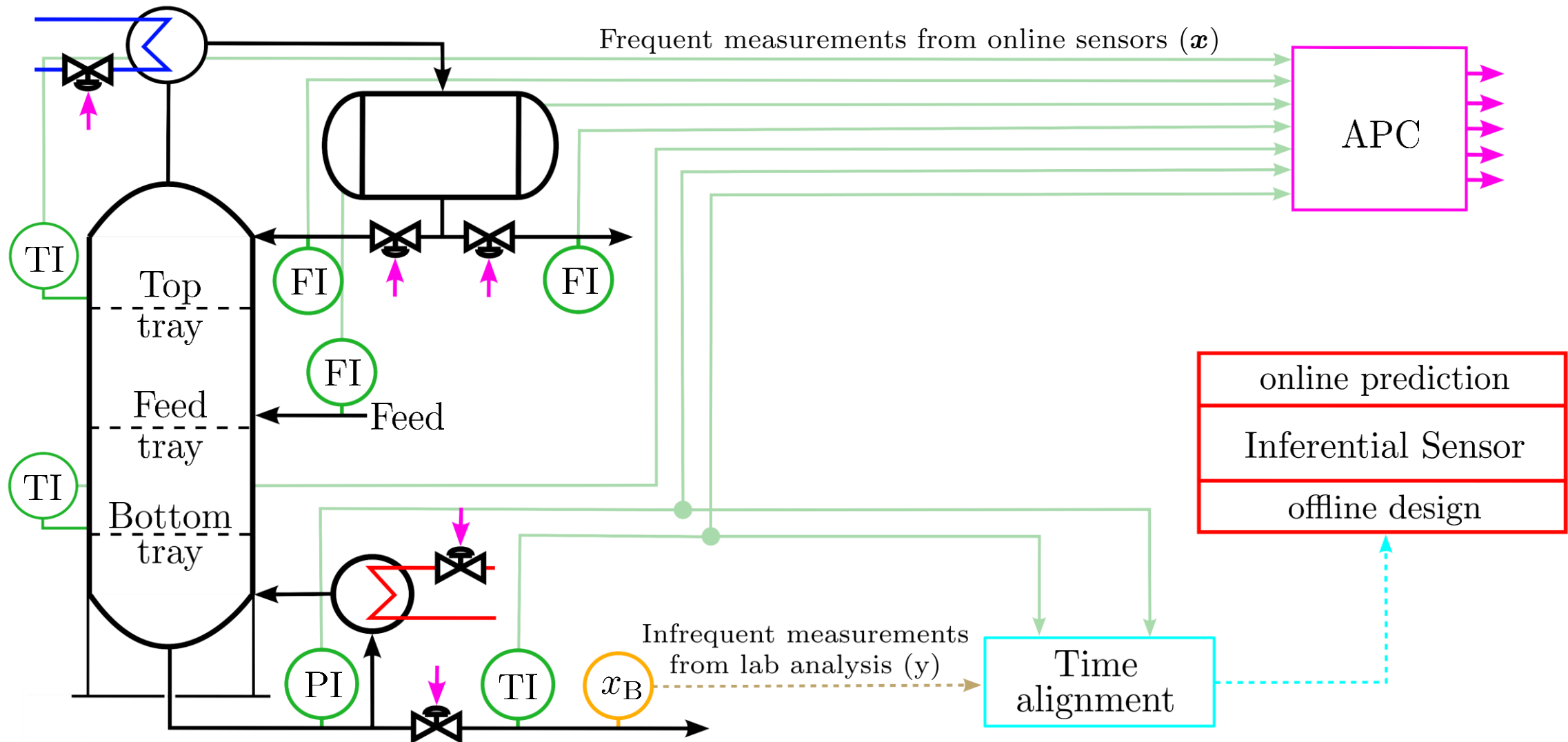
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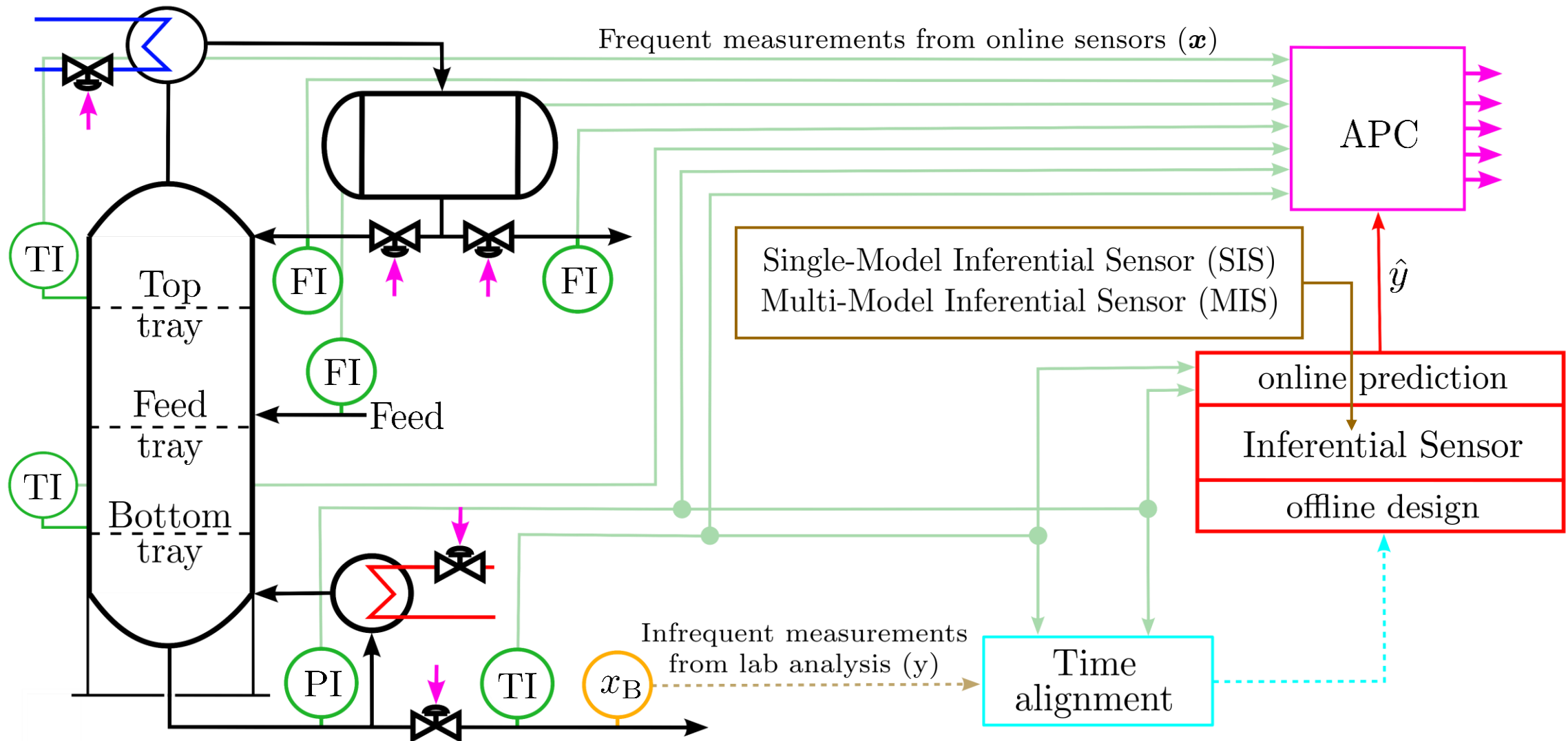
Motivation: Inferential Sensors

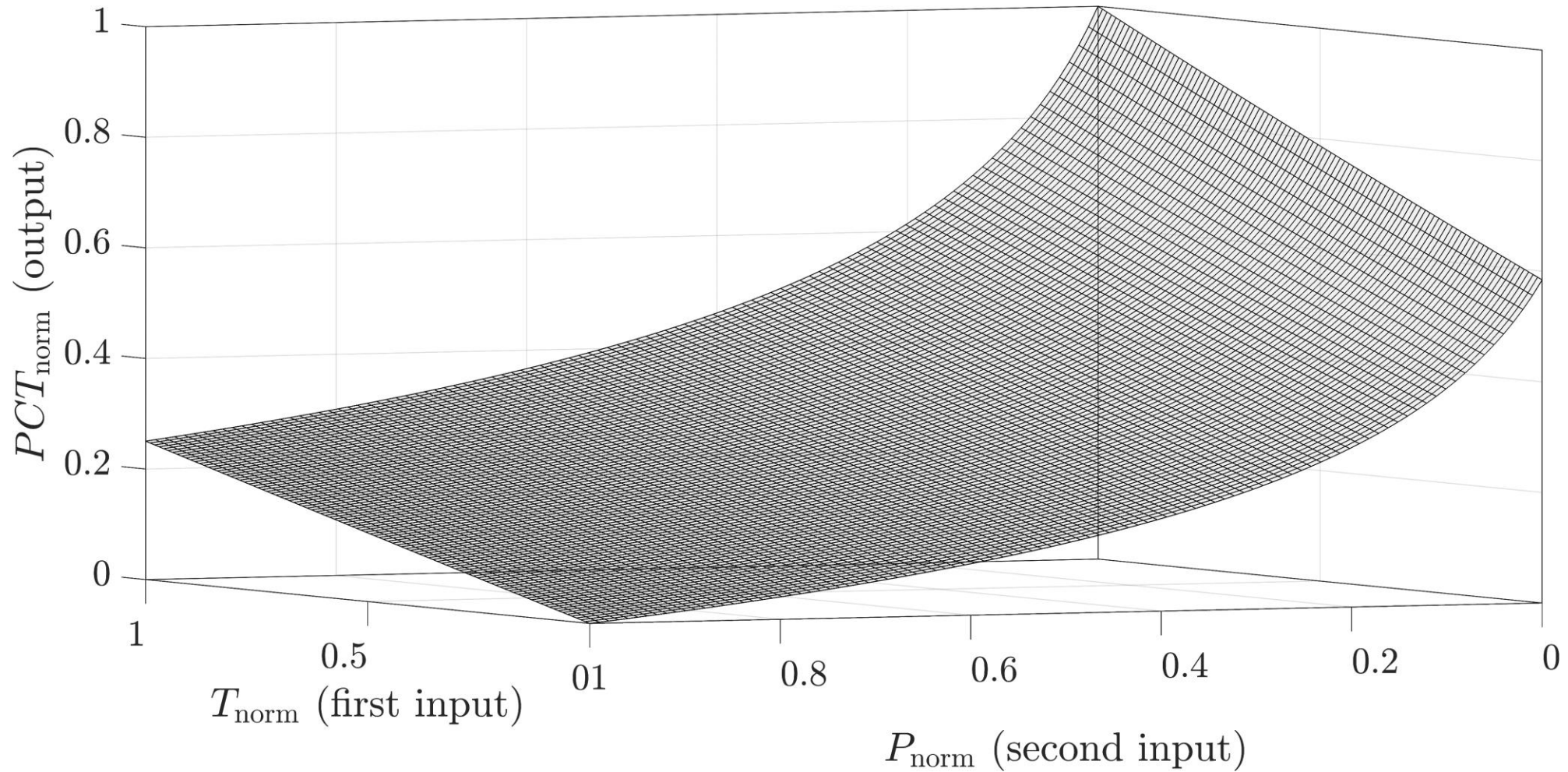


Motivation: Inferential Sensors

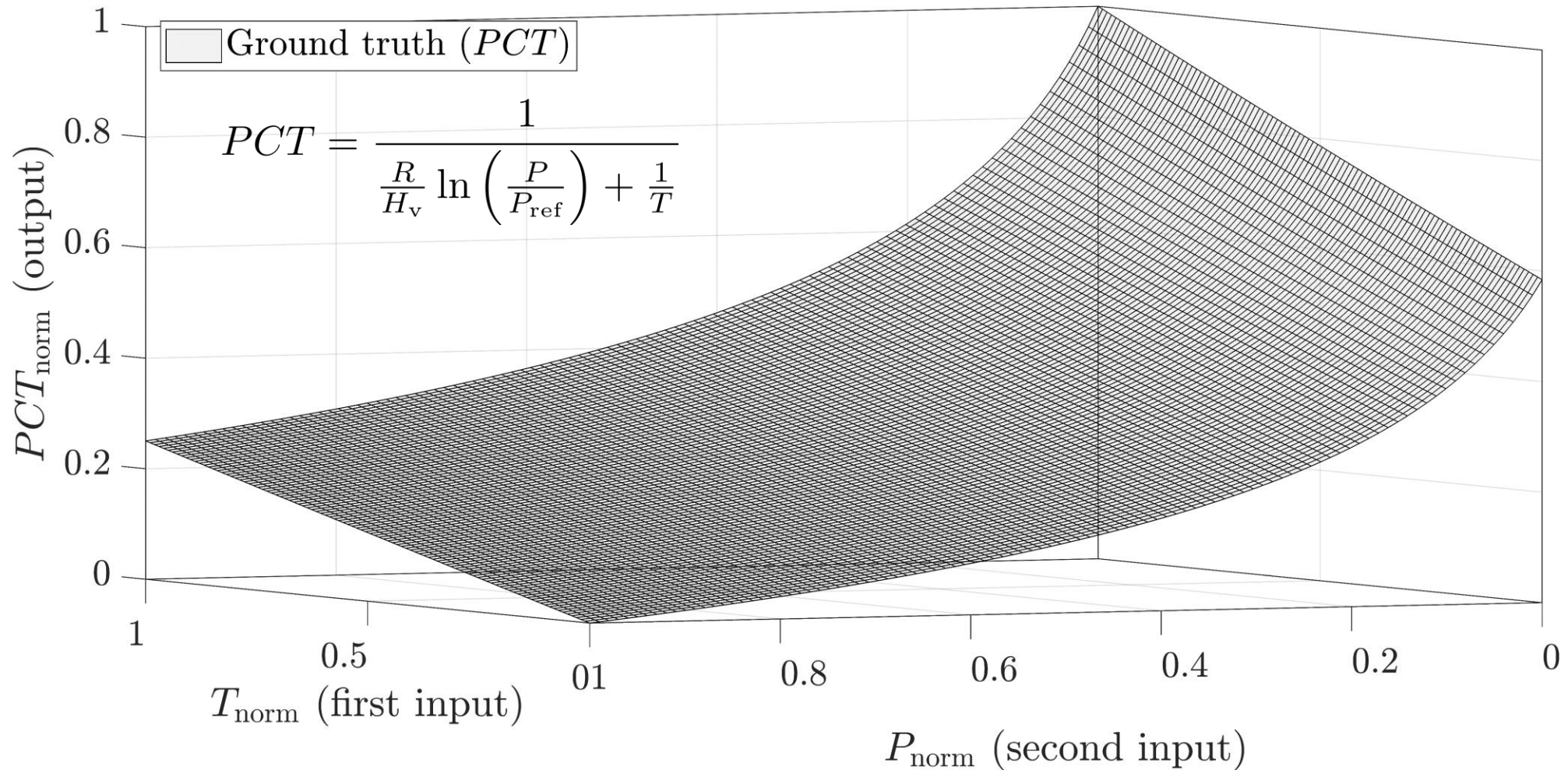


Motivation: Inferential Sensors

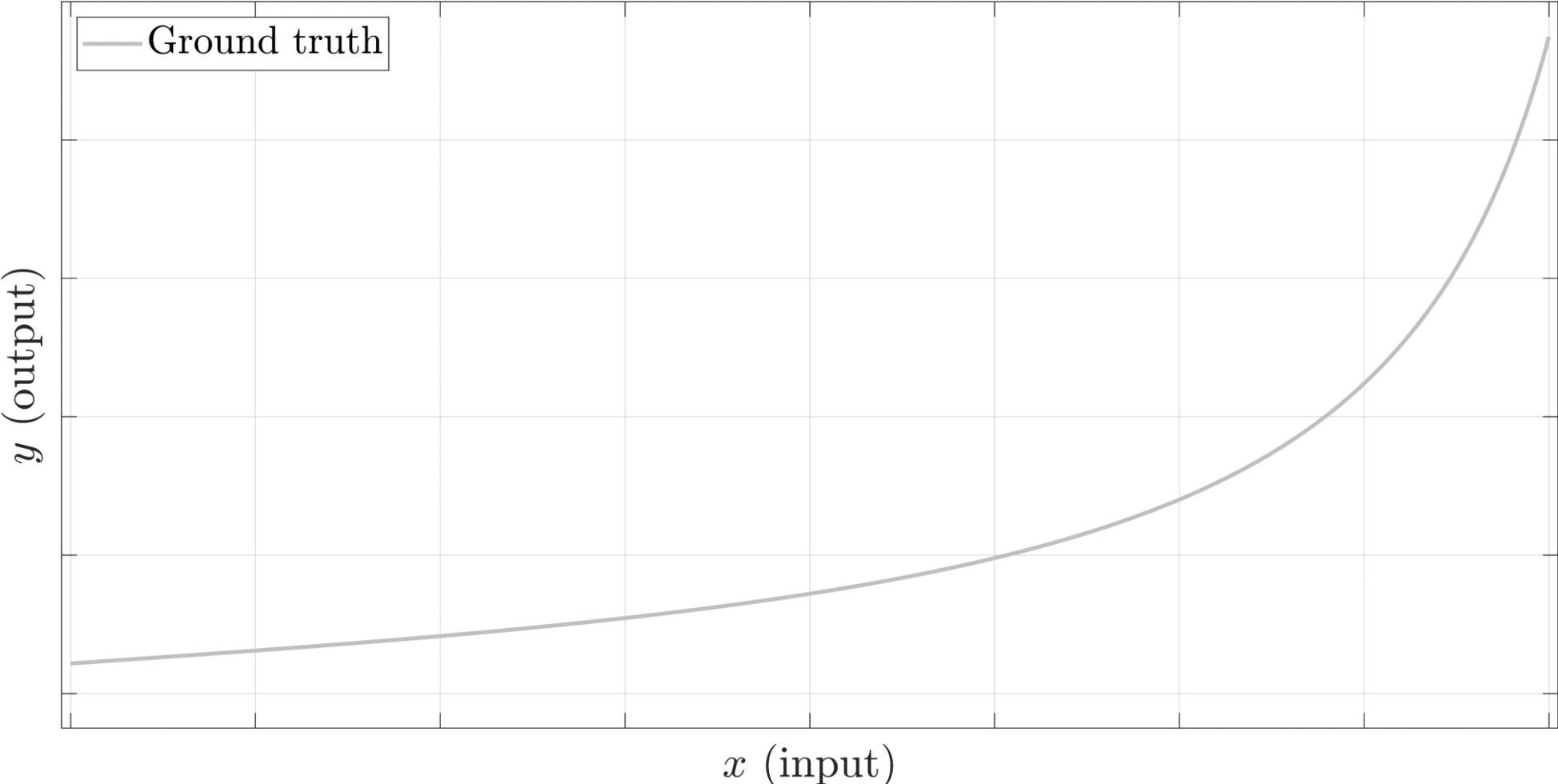




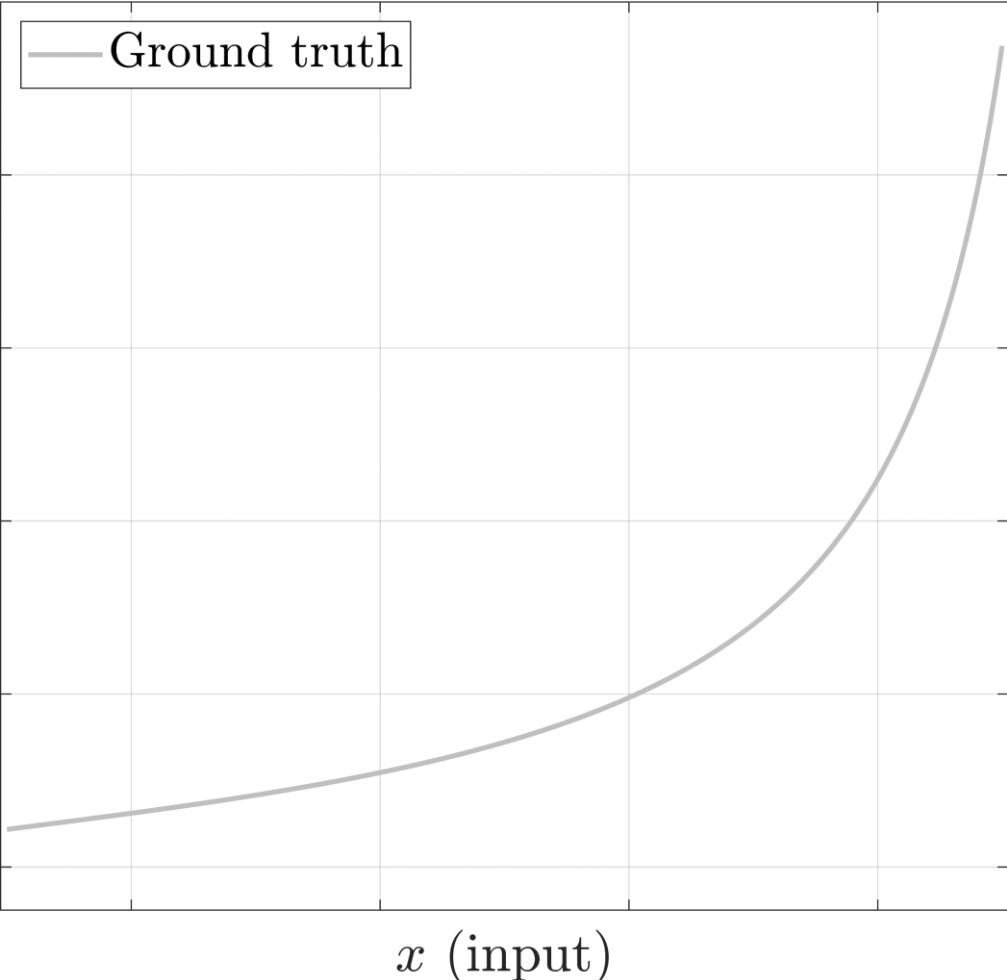
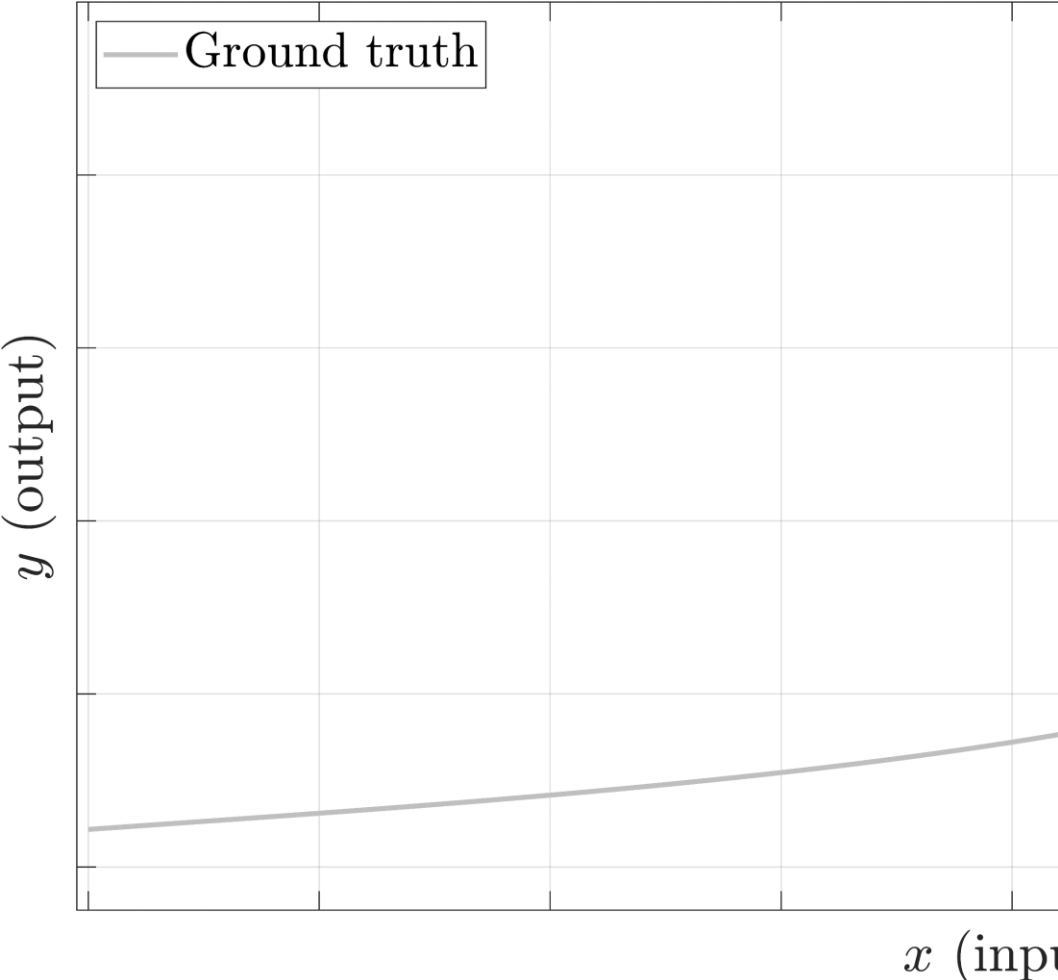
Case study: 3D

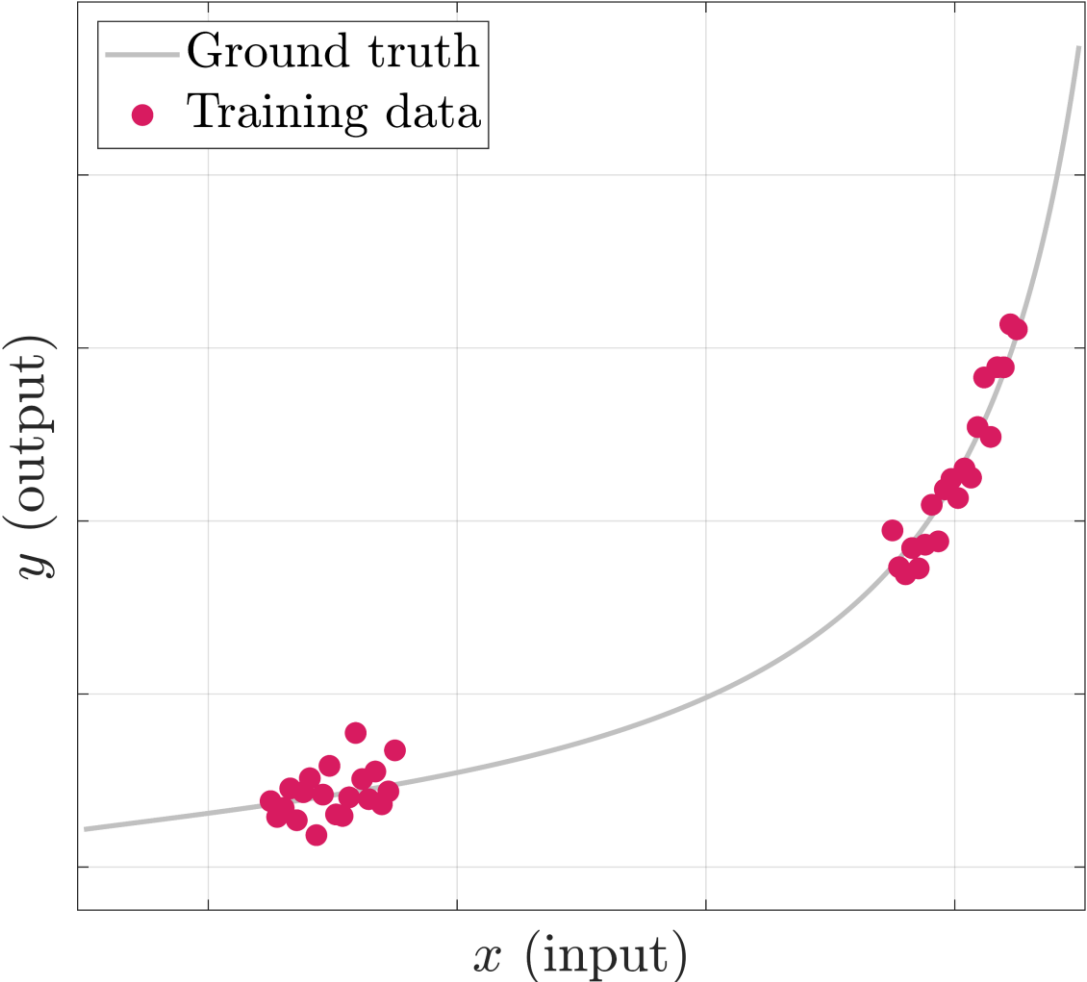


Case study: 3D \rightarrow 2D

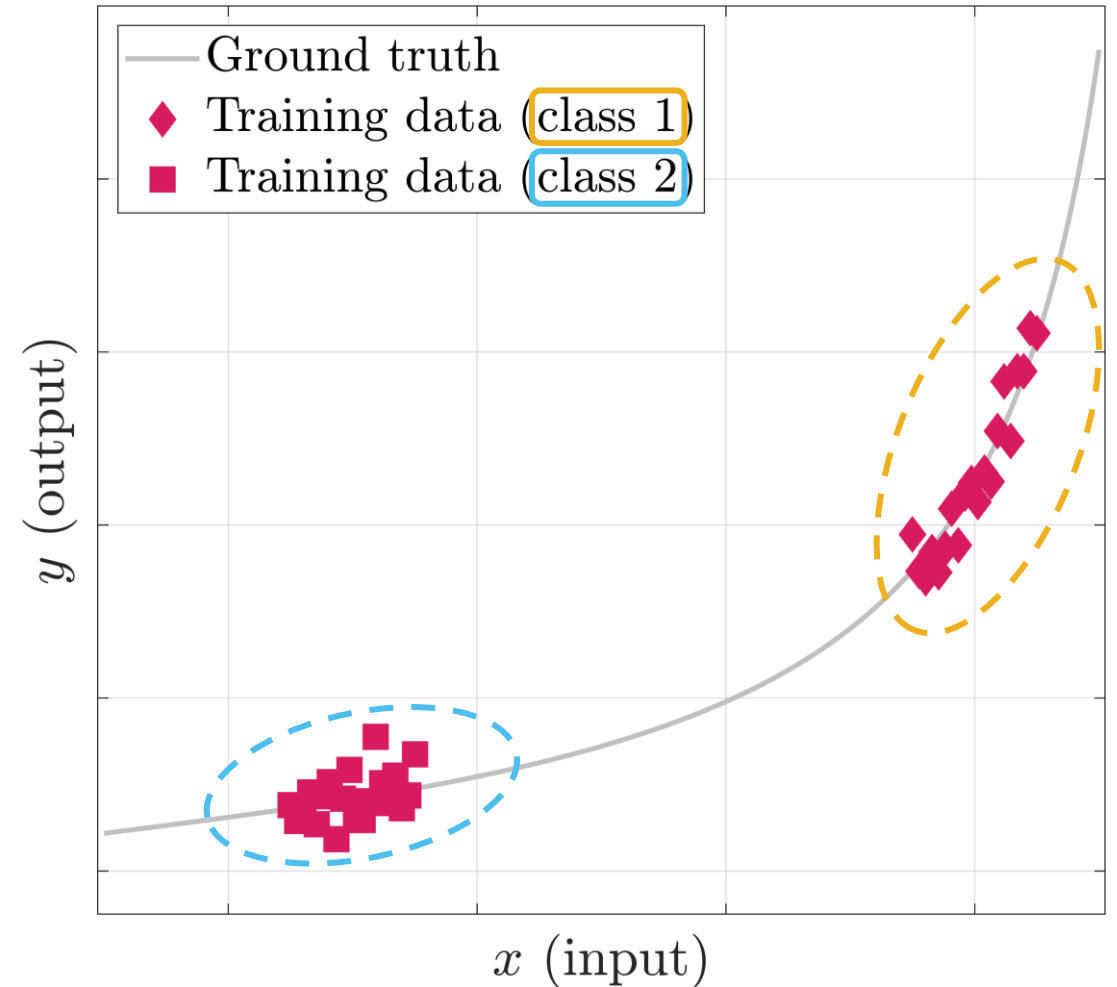


State-of-the-Art Approach





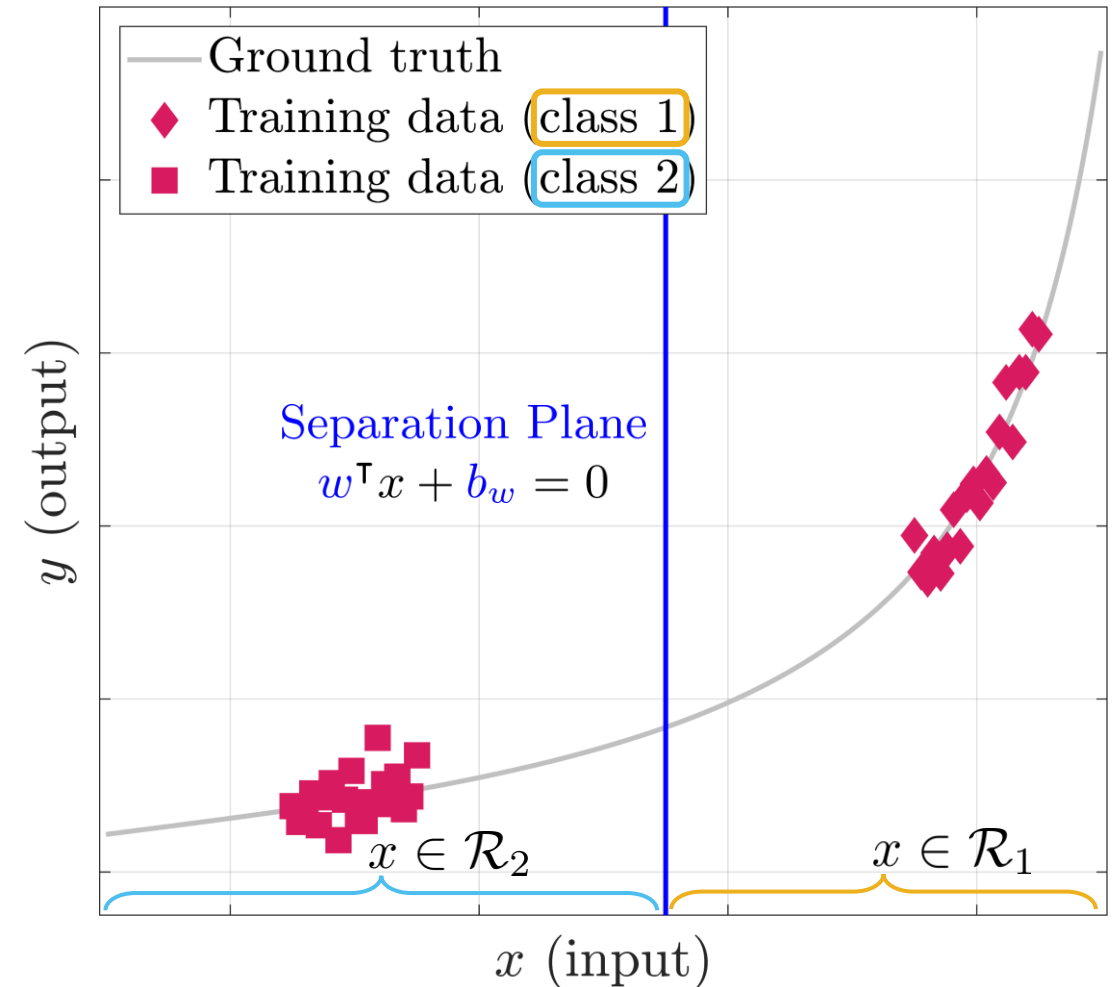
1. A priori labeling of the training dataset



1. A priori labeling of the training dataset

2. Data classification

- Method: Support Vector Machine (SVM)
- Linear separation plane: $w^T x + b_w = 0$



1. A priori labeling of the training dataset

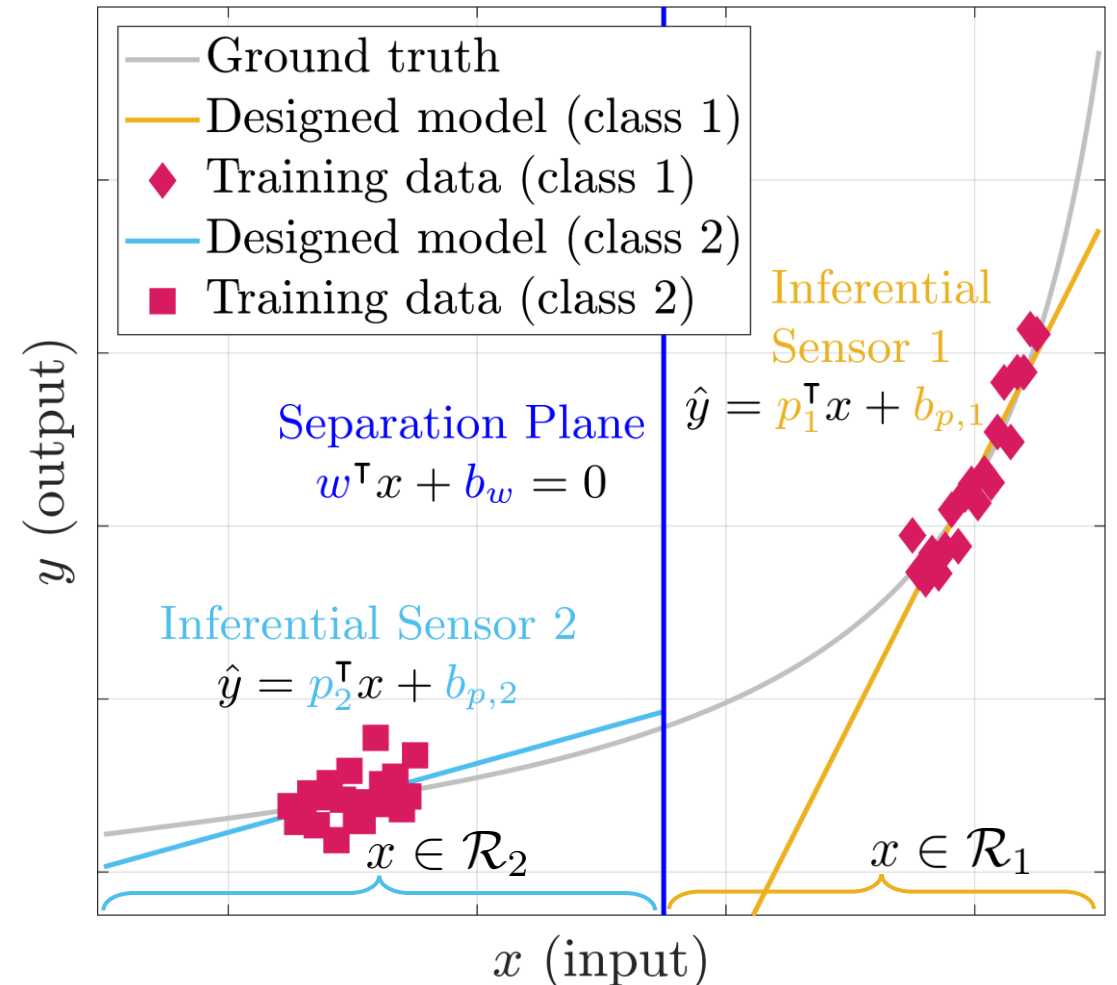
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3. Individual sensor training

$$\hat{y} = \begin{cases} p_1^T x + b_{p,1}, & \text{if } x \in \mathcal{R}_1 \\ p_2^T x + b_{p,2}, & \text{if } x \in \mathcal{R}_2 \end{cases}$$

calculation of model parameters
 $p_1, b_{p,1}, p_2, b_{p,2}$



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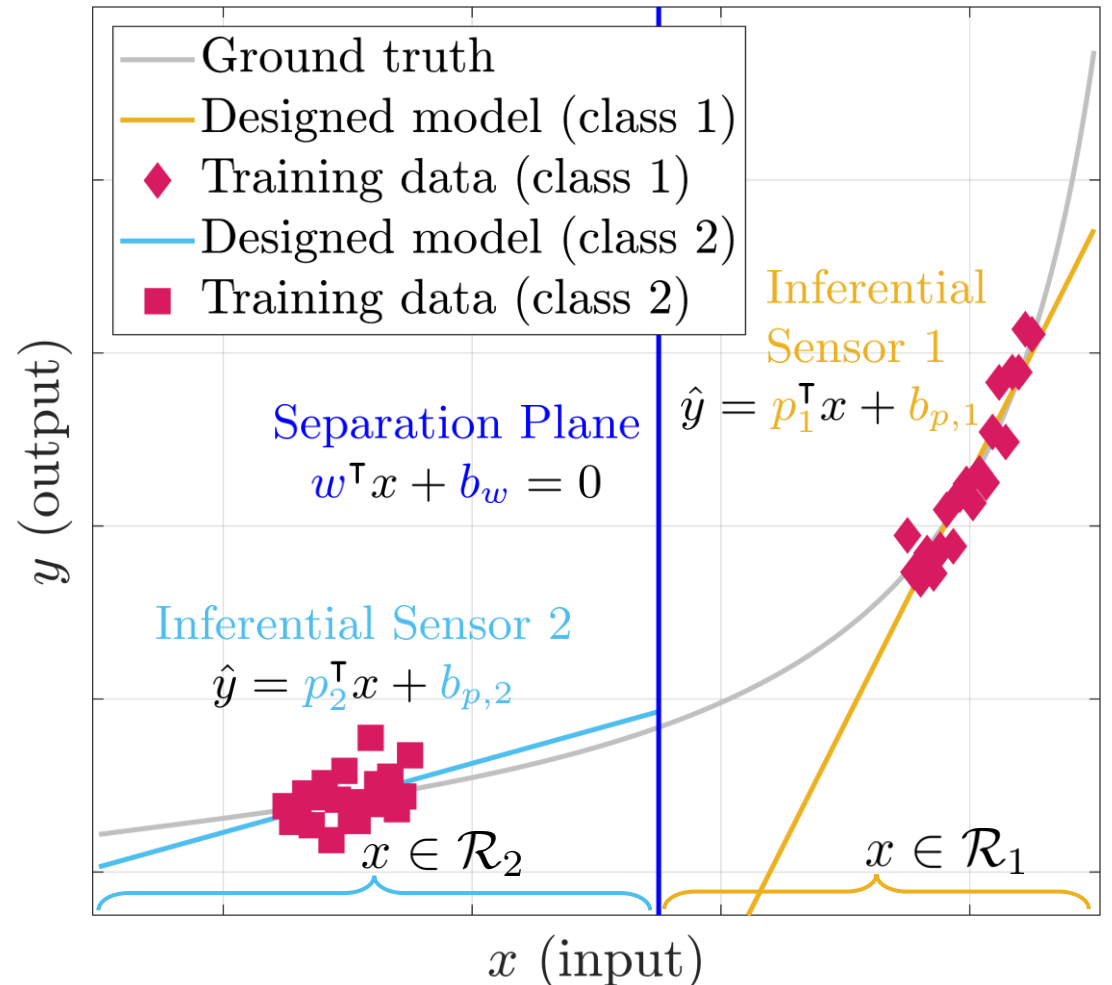
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MIS-SotA



1. A priori labeling of the training dataset
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3. Individual sensor training

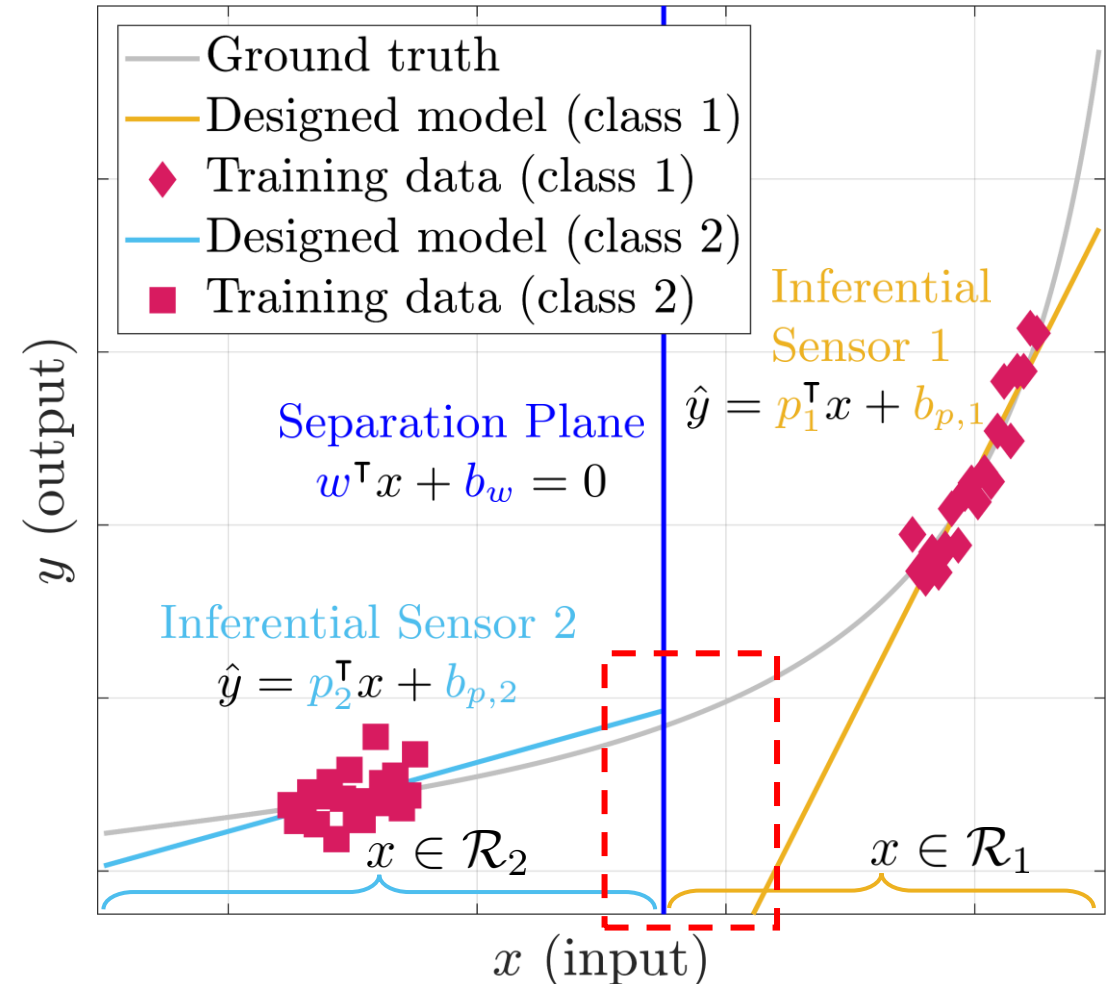
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MIS-SotA

Main Challenges:

!! Discontinuity of MIS models



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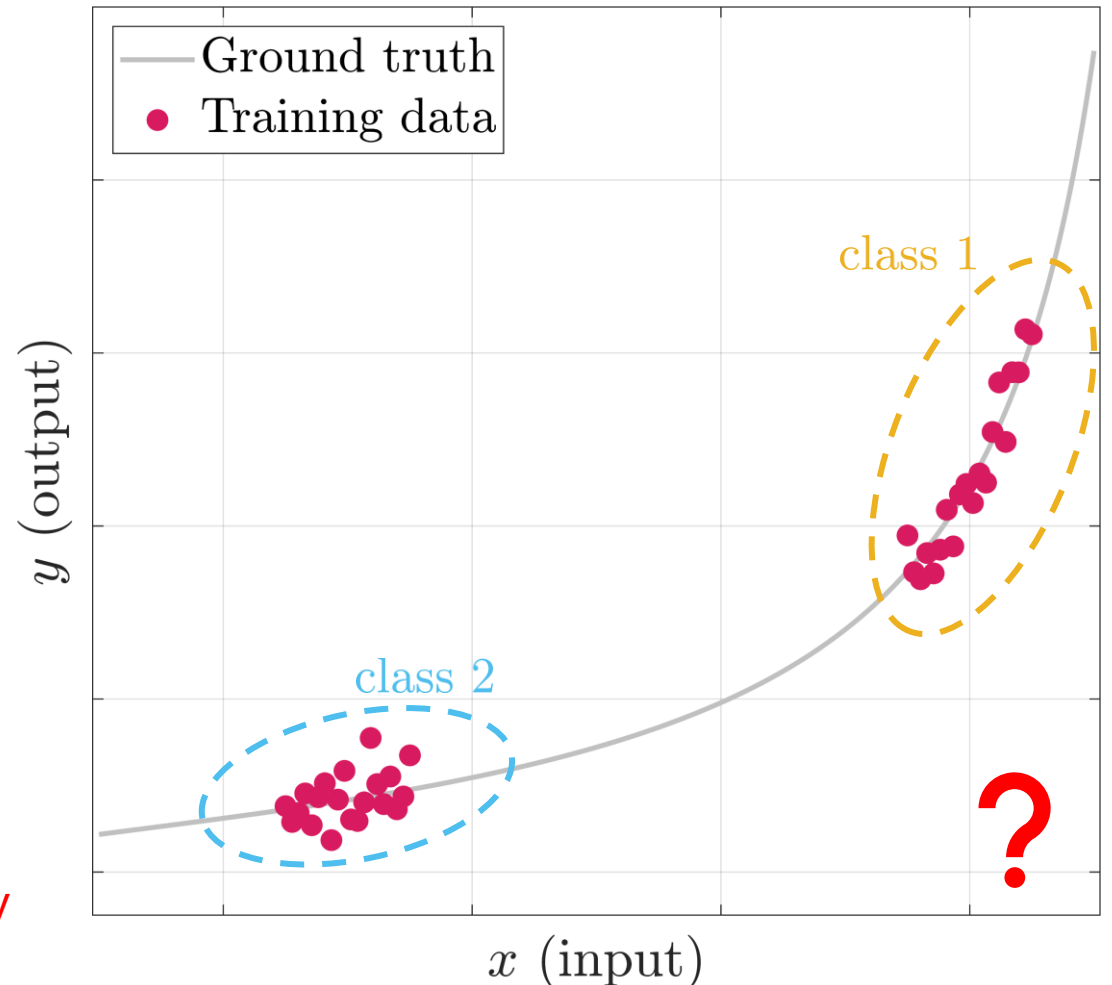
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MIS-SotA

Main Challenges:

!! Discontinuity of MIS models

!! Unknown impact of a priori labeling on the MIS accuracy



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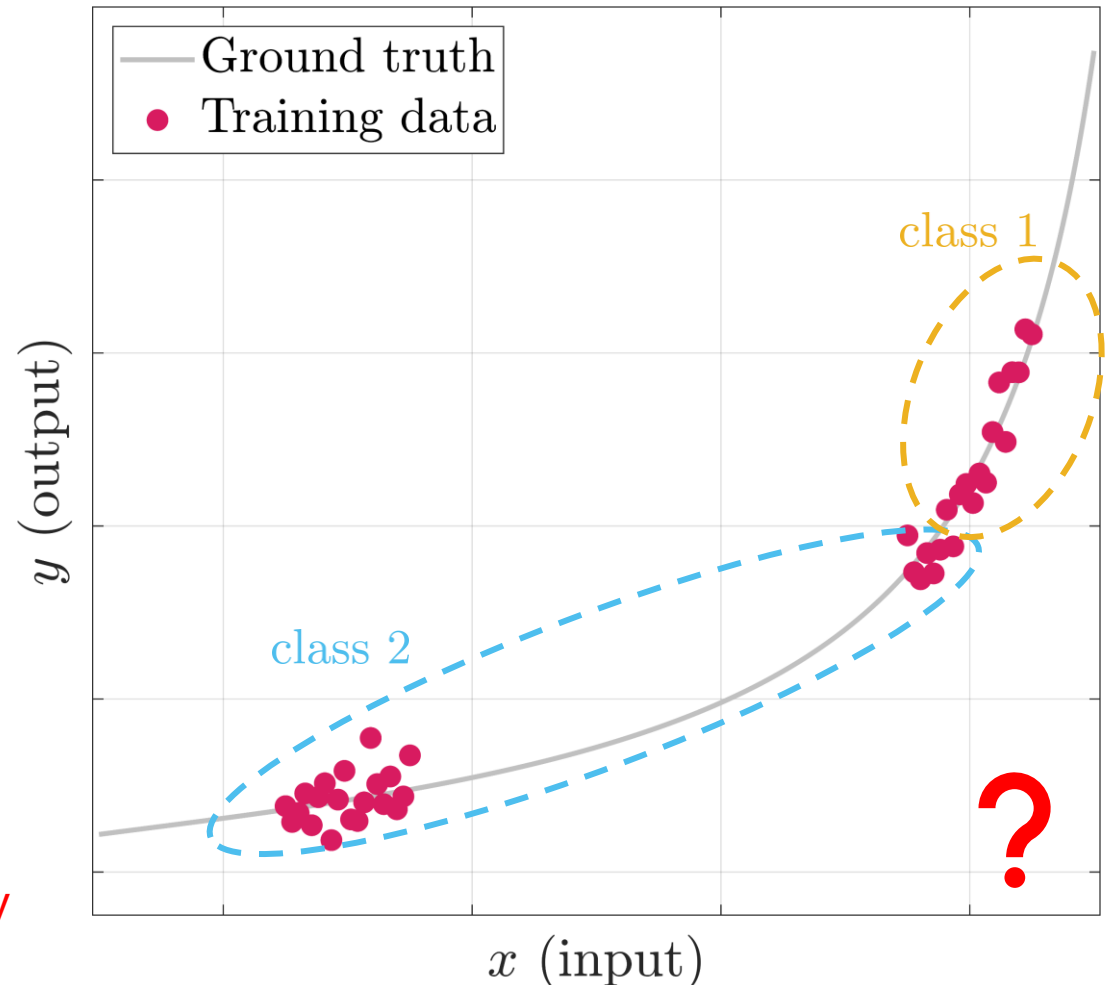
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MIS-SotA

Main Challenges:

!! Discontinuity of MIS models

!! Unknown impact of a priori labeling on the MIS accuracy



1. A priori labeling of the training dataset

2. Data classification & sensor training

$$\min_{\substack{e \geq 0, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

↑ sum of squared errors ↑ slack variables

$$\text{s.t.} \quad (2z_i - 1)(w^\top x_i + b_w) \geq 1 - e_i$$

$$\forall i = \{1, 2, \dots, n\}$$

MIS-SotA (enhanced)

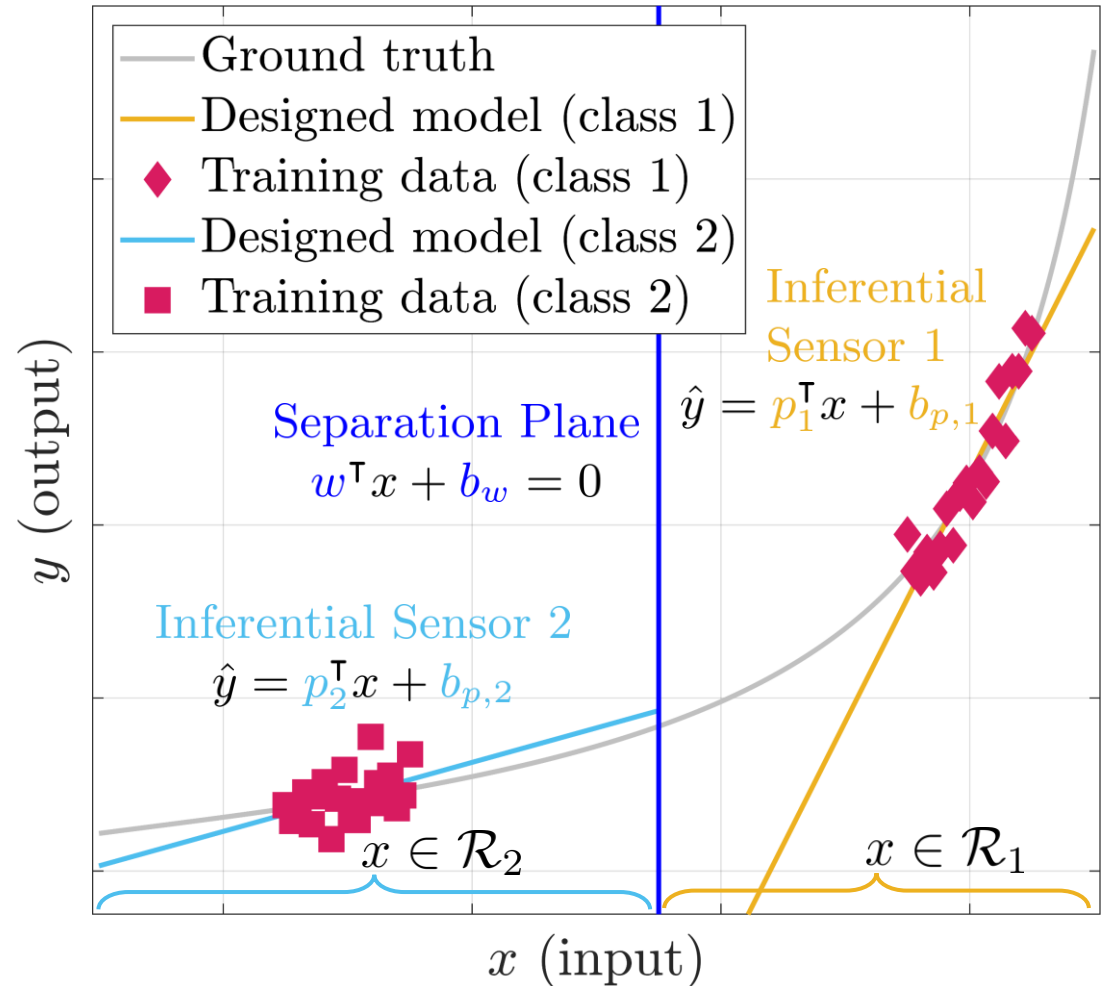
Binary variables

$$z_i = \begin{cases} 1, & \text{if } x_i \in \mathcal{R}_1 \\ 0, & \text{if } x_i \in \mathcal{R}_2 \end{cases}$$

number of measurements in a class

$$n = n_1 + n_2$$

$$\forall i = \{1, 2, \dots, n\}$$



1. A priori labeling of the training dataset

2. Data classification & sensor training

$$\min_{\substack{e \geq 0, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

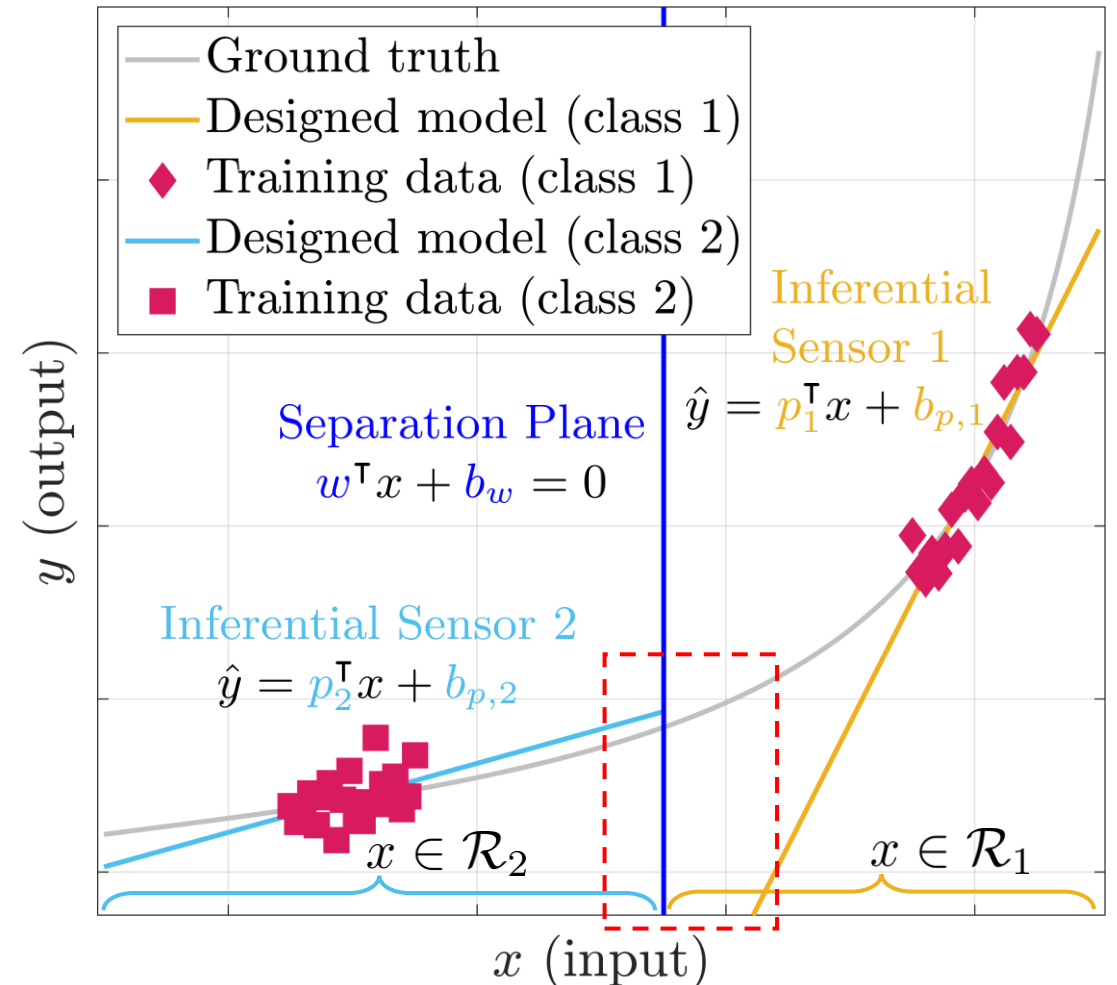
$$\text{s.t.} \quad (2z_i - 1) (w^\top x_i + b_w) \geq 1 - e_i$$

$$\forall i = \{1, 2, \dots, n\}$$

!! Discontinuity of MIS models

The continuity constraints:

$$p_1 - p_2 - w = 0, \quad b_{p,1} - b_{p,2} - b_w = 0$$



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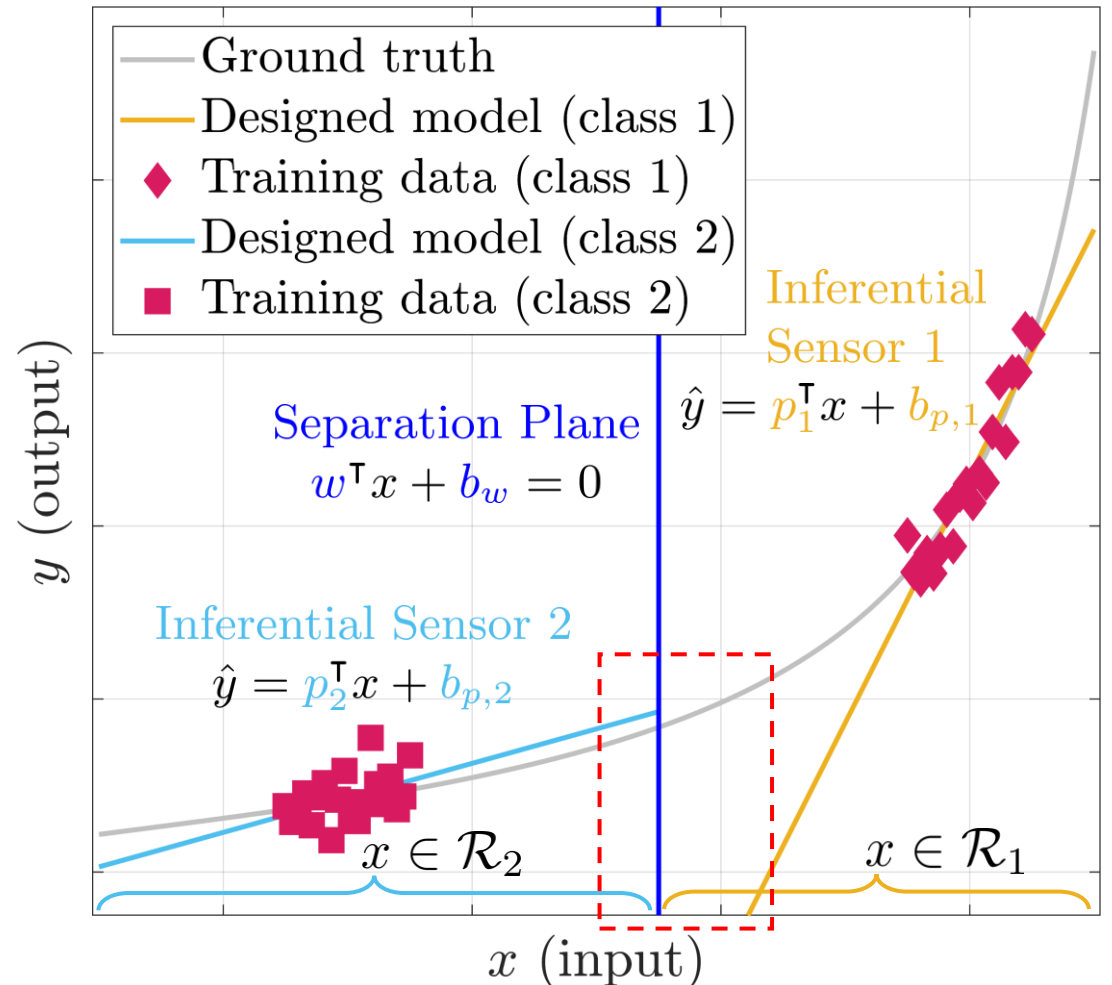
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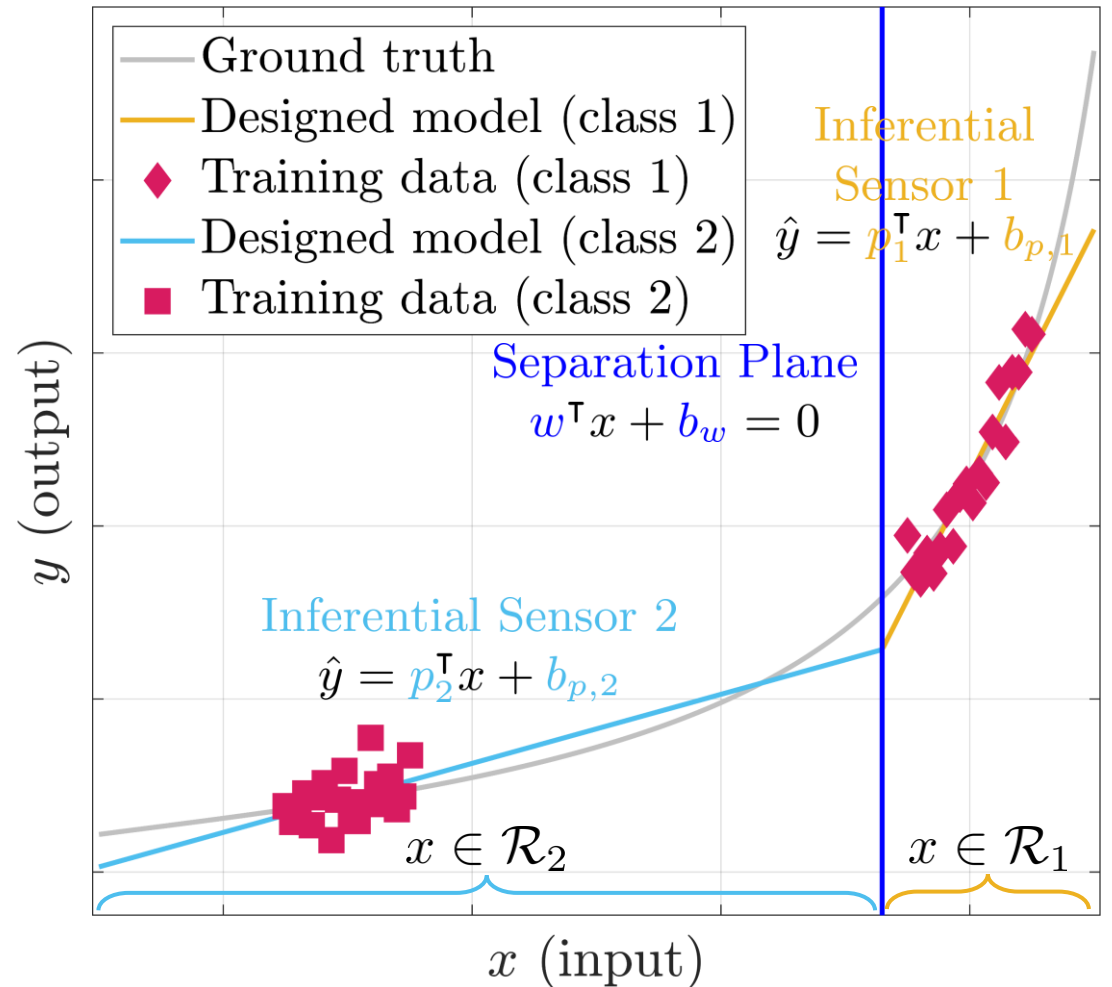
$$\min_{\substack{e \geq 0, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

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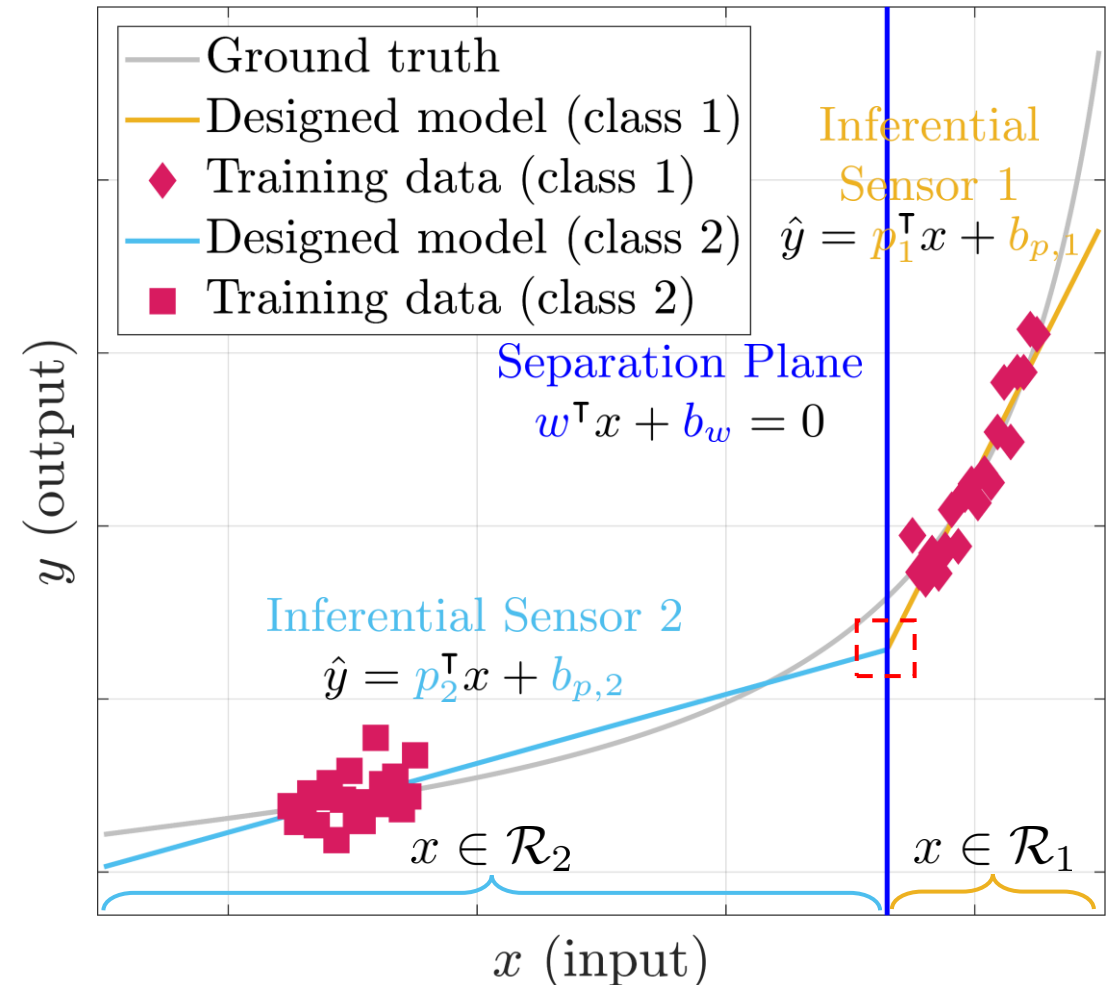
$$\min_{\substack{e \geq 0, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

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✓ Continuity of MIS models



1. A priori labeling of the training dataset

2. Data classification & sensor training

$$\min_{e \geq 0, w, b_w, p_1, b_{p,1}, p_2, b_{p,2}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

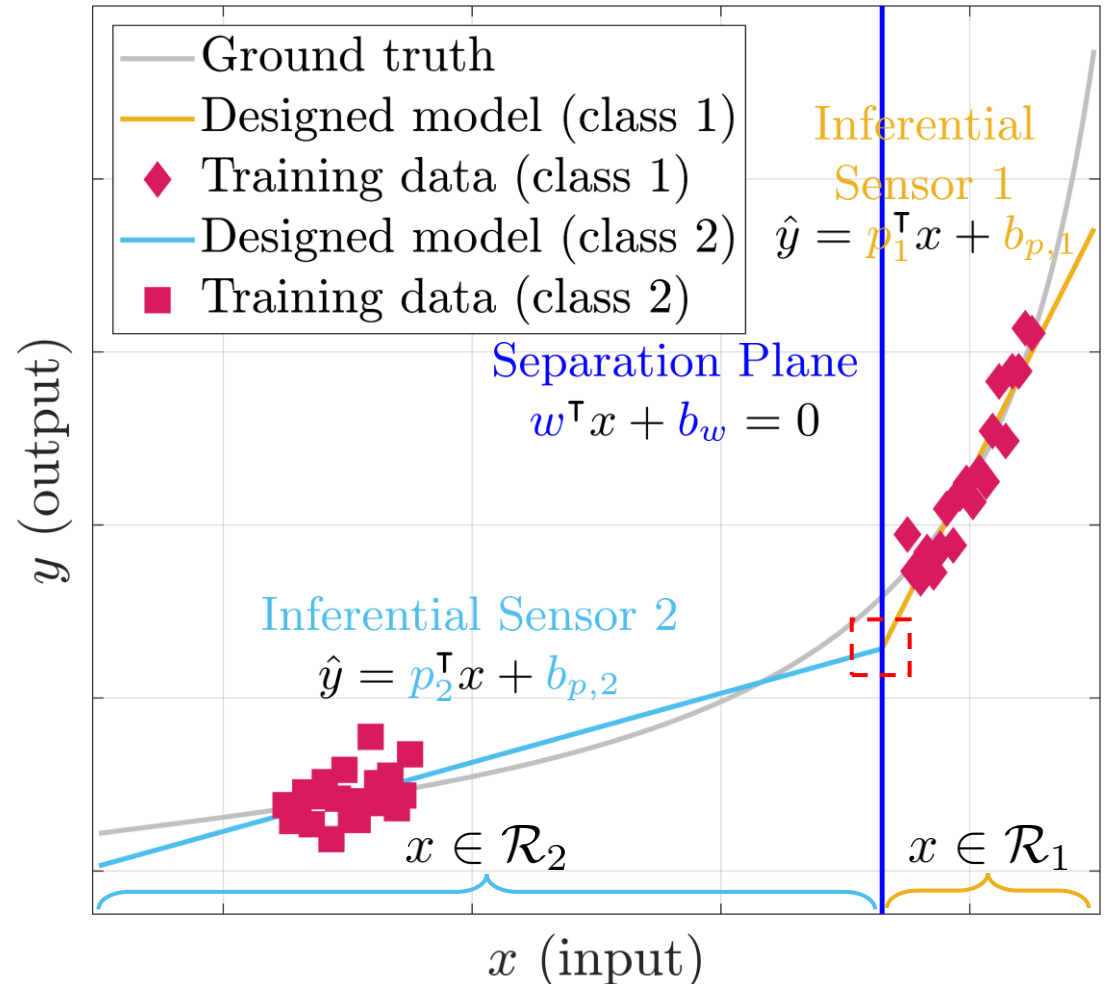
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$$p_1 - p_2 - w = 0, \quad b_{p,1} - b_{p,2} - b_w = 0$$

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MIS-con

✓ Continuity of MIS models



1. A priori labeling of the training dataset

2. Data classification & sensor training

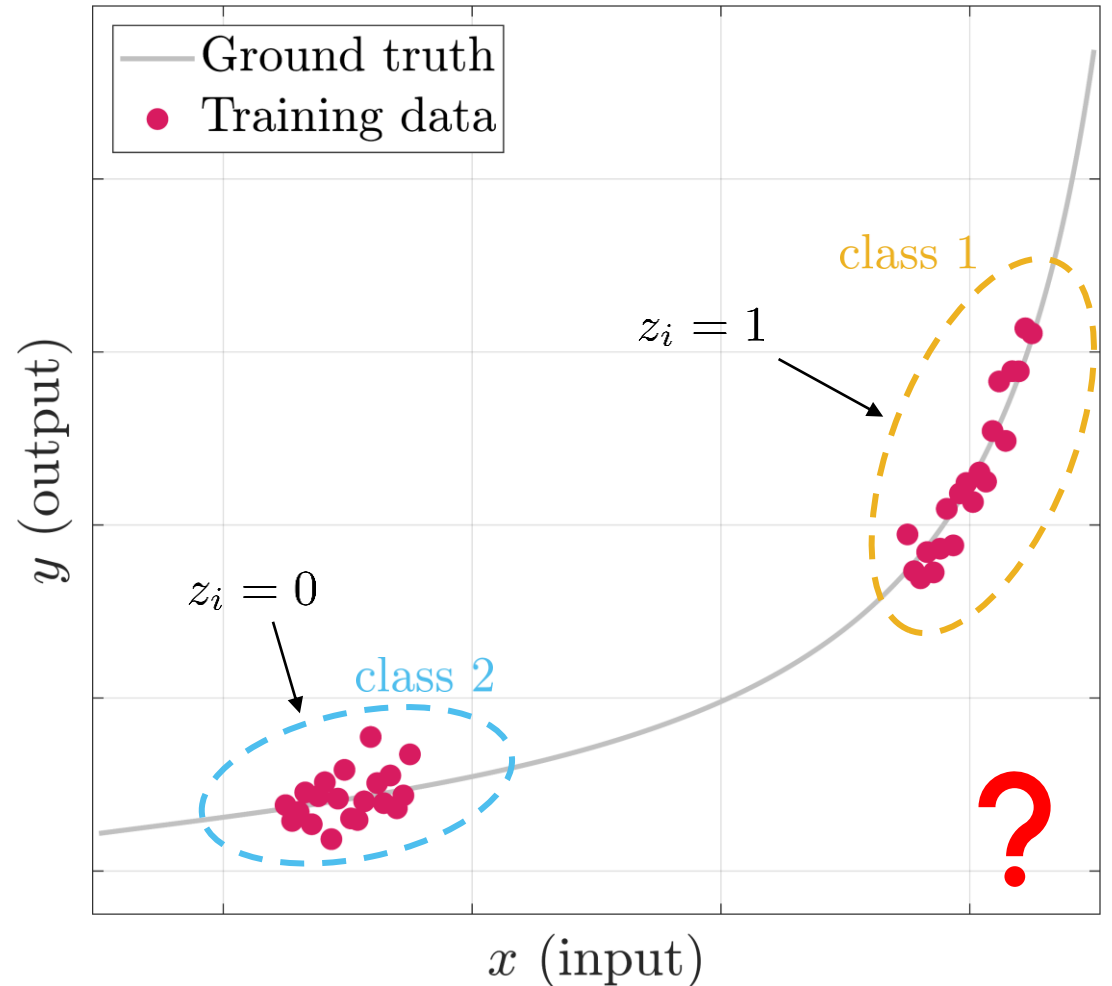
$$\min_{\substack{e \geq 0, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

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$$\forall i = \{1, 2, \dots, n\}$$

!! Unknown impact of a priori labeling on the MIS accuracy



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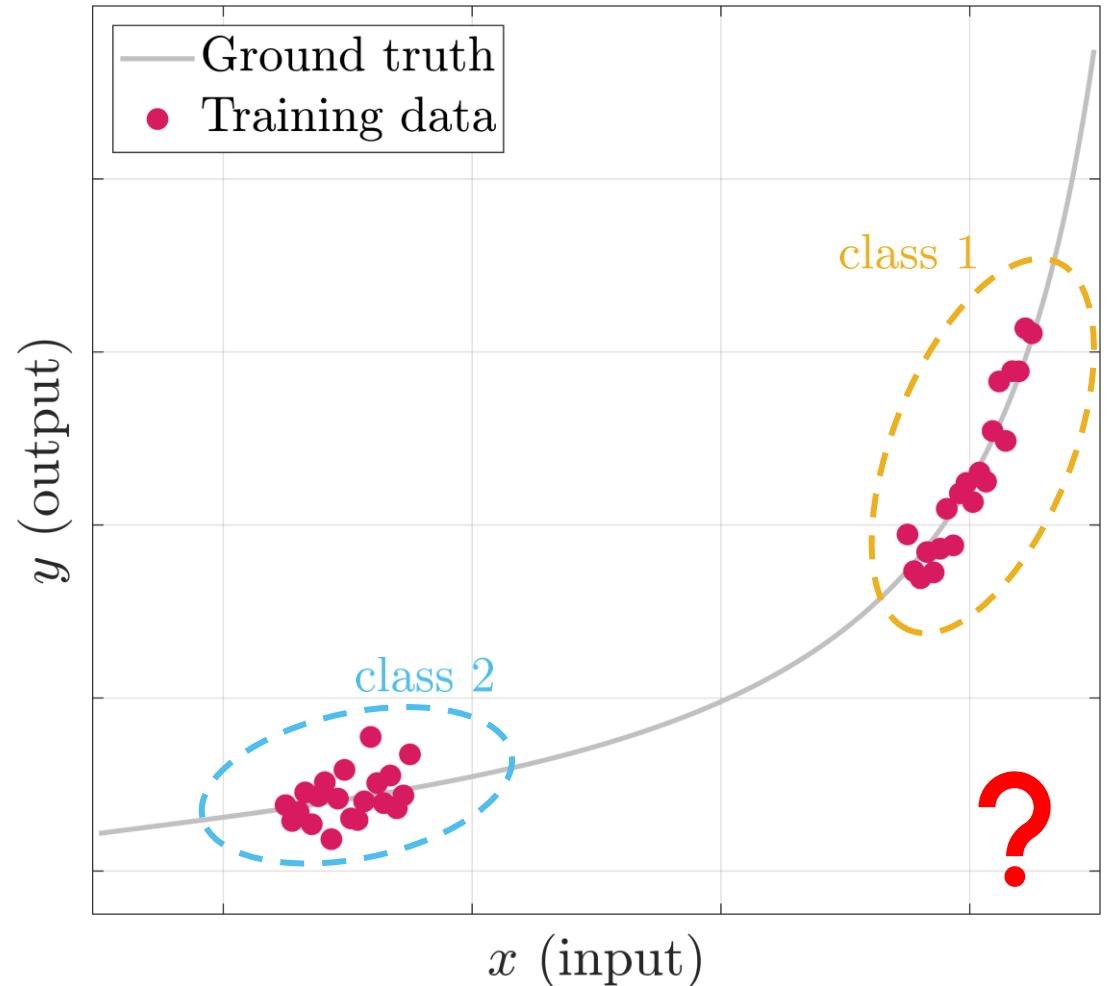
$$\text{s.t.} \quad (2z_i - 1) (w^\top x_i + b_w) \geq 1 - e_i$$

$$p_1 - p_2 - w = 0, \quad b_{p,1} - b_{p,2} - b_w = 0$$

$$\forall i = \{1, 2, \dots, n\}$$

!! Unknown impact of a priori labeling on the MIS accuracy

⇒ z will be optimized!



Data labeling & Data classification & Sensor training

simultaneously

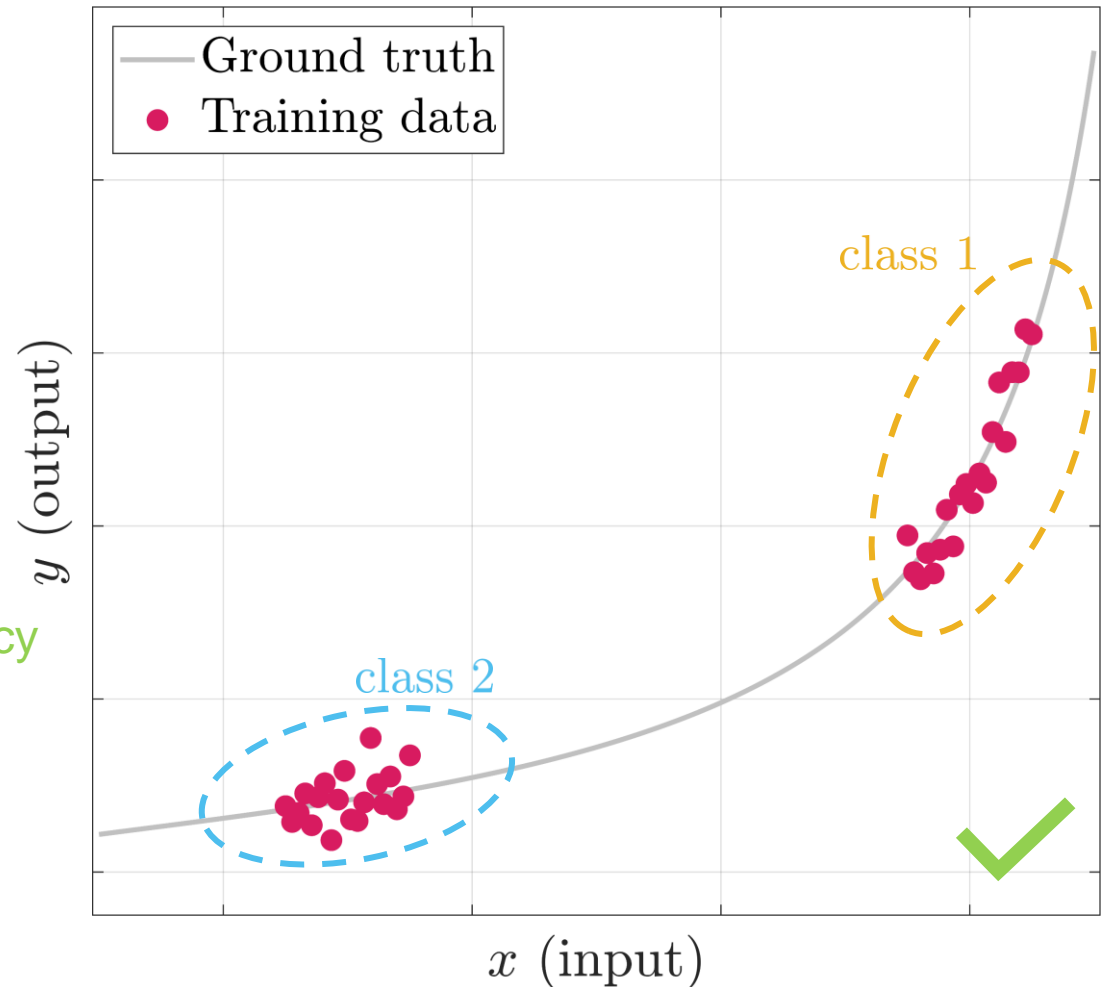
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$$\text{s.t.} \quad (2z_i - 1) (w^\top x_i + b_w) \geq 1 - e_i$$

$$p_1 - p_2 - w = 0, \quad b_{p,1} - b_{p,2} - b_w = 0$$

$$\forall i = \{1, 2, \dots, n\}, \quad z \in \{0, 1\}^n$$

✓ Considered impact of a priori labeling on the MIS accuracy



Data labeling & Data classification & Sensor training

simultaneously

$$\min_{\substack{e \geq 0, z, w, b_w \\ p_1, b_{p,1}, p_2, b_{p,2}}} \sum_{i=1}^n \left[z_i \text{SSE}_{1,i} + (1 - z_i) \text{SSE}_{2,i} \right] + \alpha \|w\|_2^2 + \beta \|e\|_1$$

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$$\forall i = \{1, 2, \dots, n\}, \quad z \in \{0, 1\}^n$$

MIS-con-lab

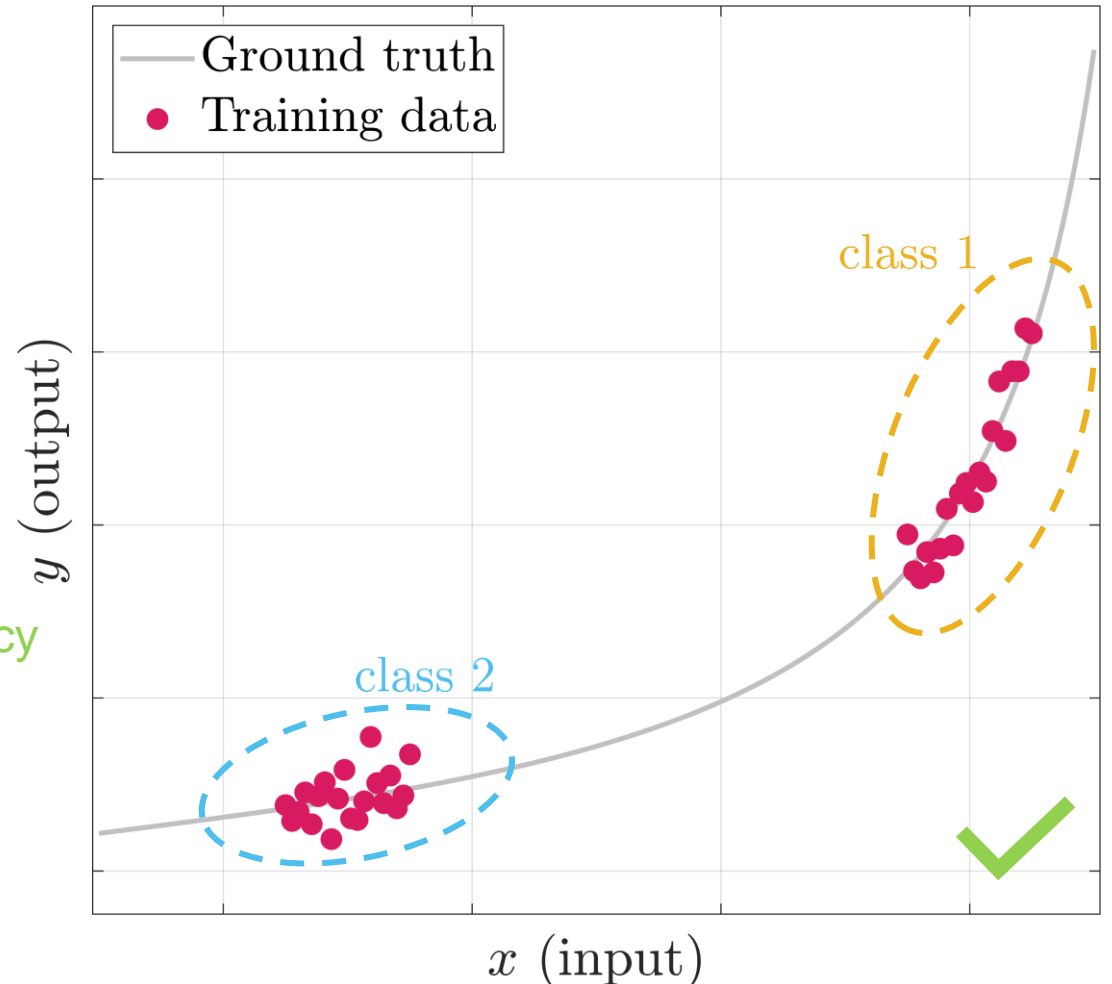
✓ Considered impact of a priori labeling on the MIS accuracy

Considered solvers

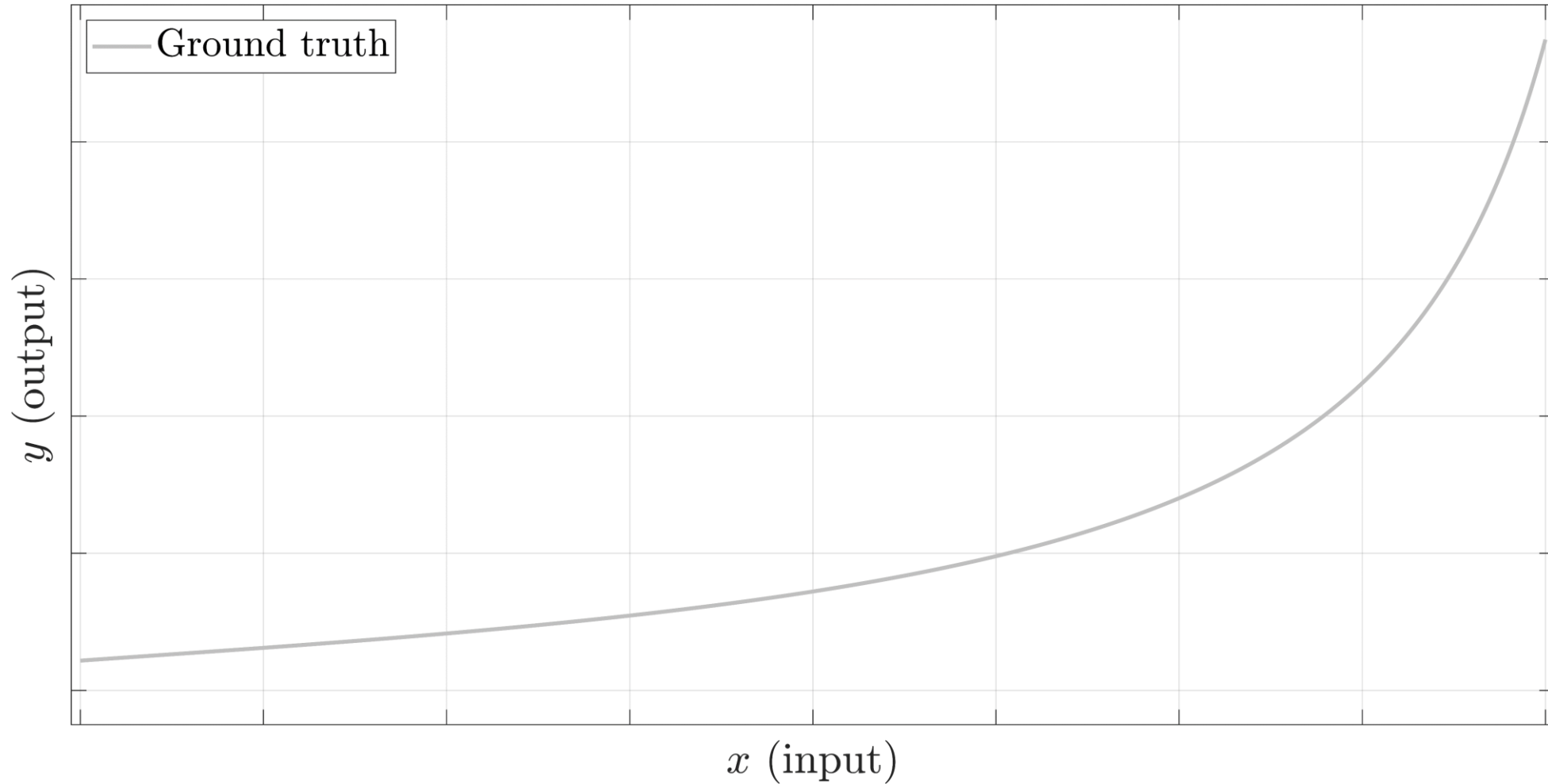
⇒ BARON: MIS-con-lab (bar)

⇒ BARON with heuristic termination: MIS-con-lab (bar,ht)

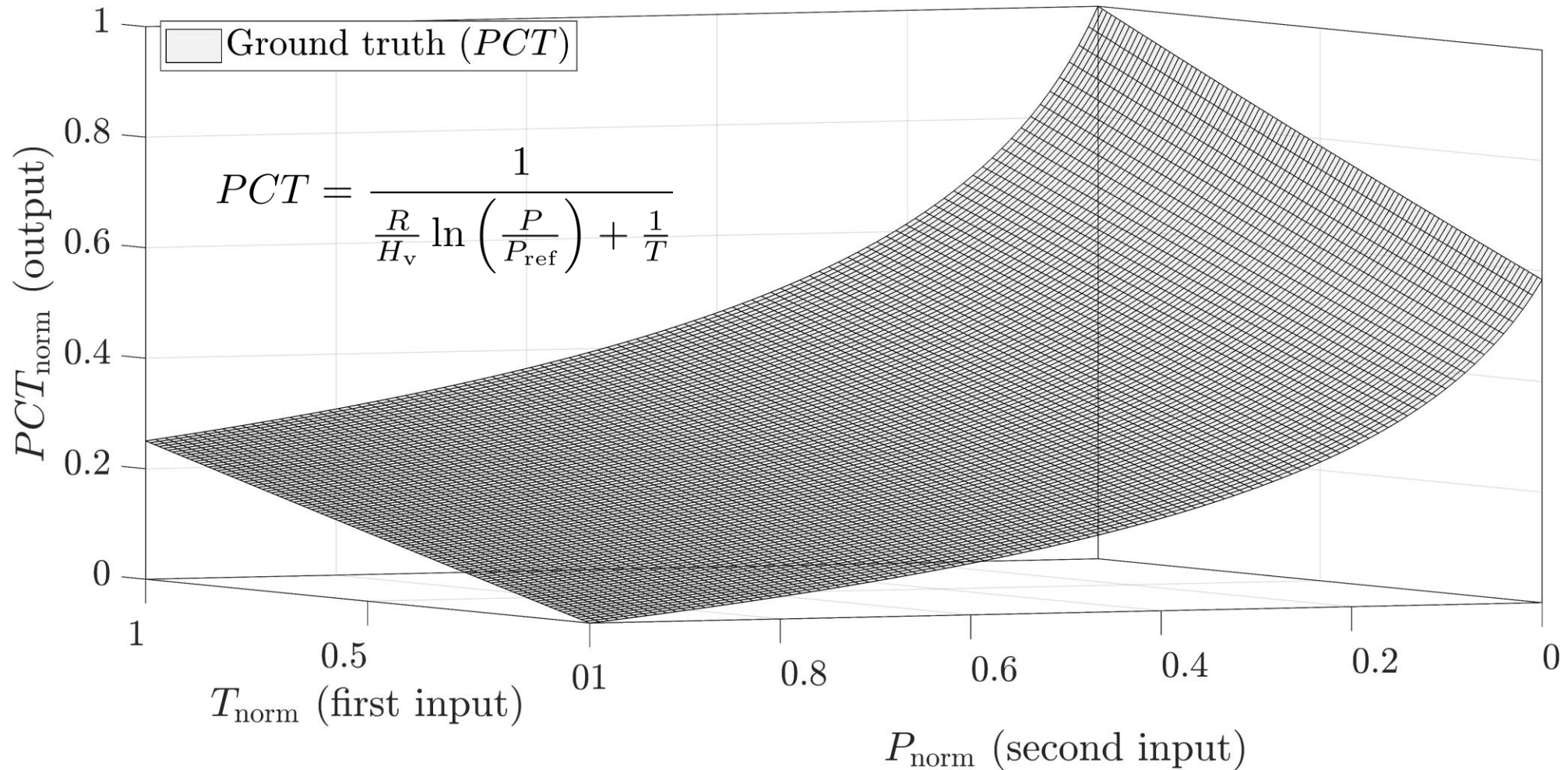
⇒ Gurobi with big-M reformulations: MIS-con-lab (gur)

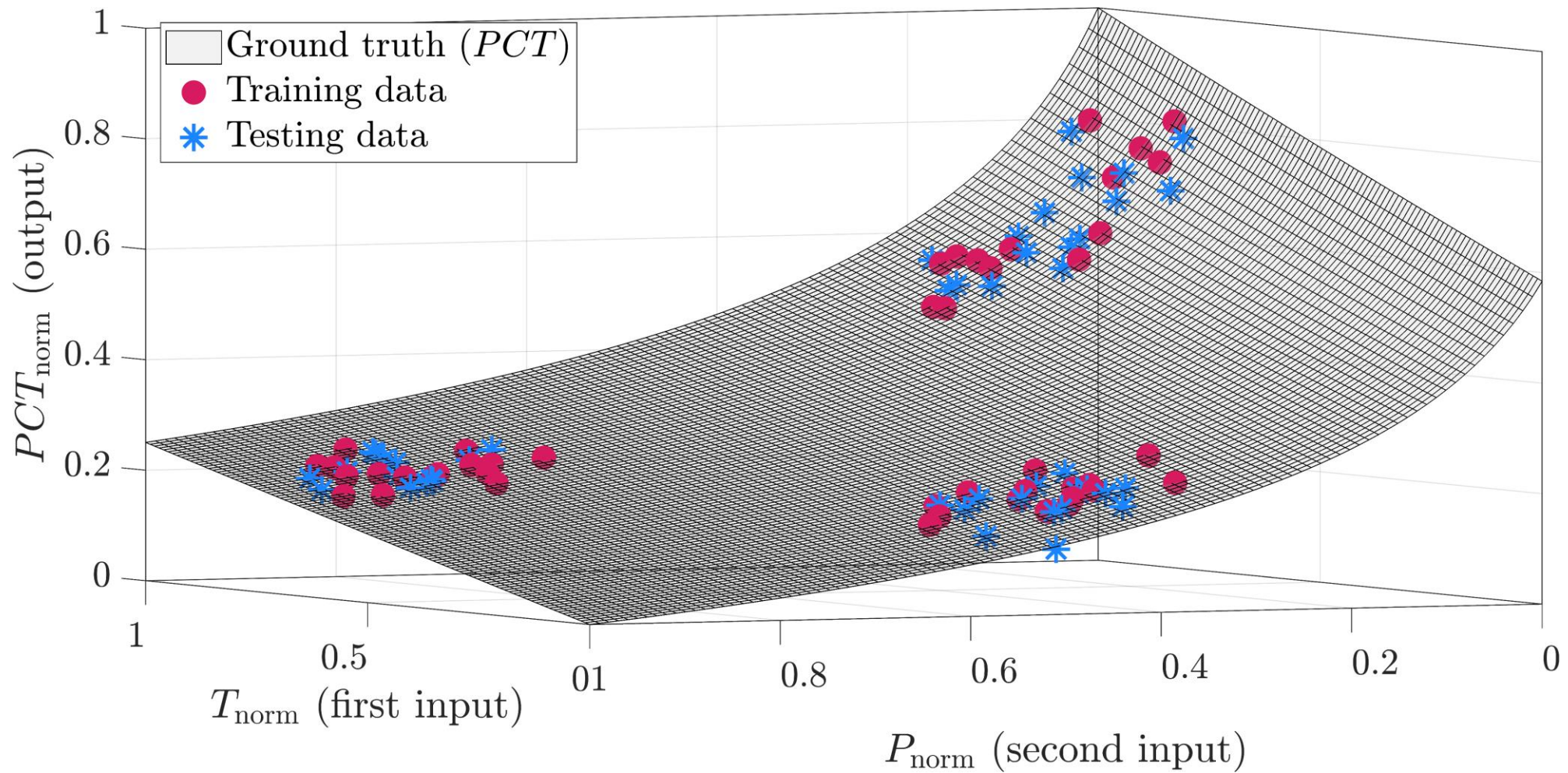


Case study: 2D



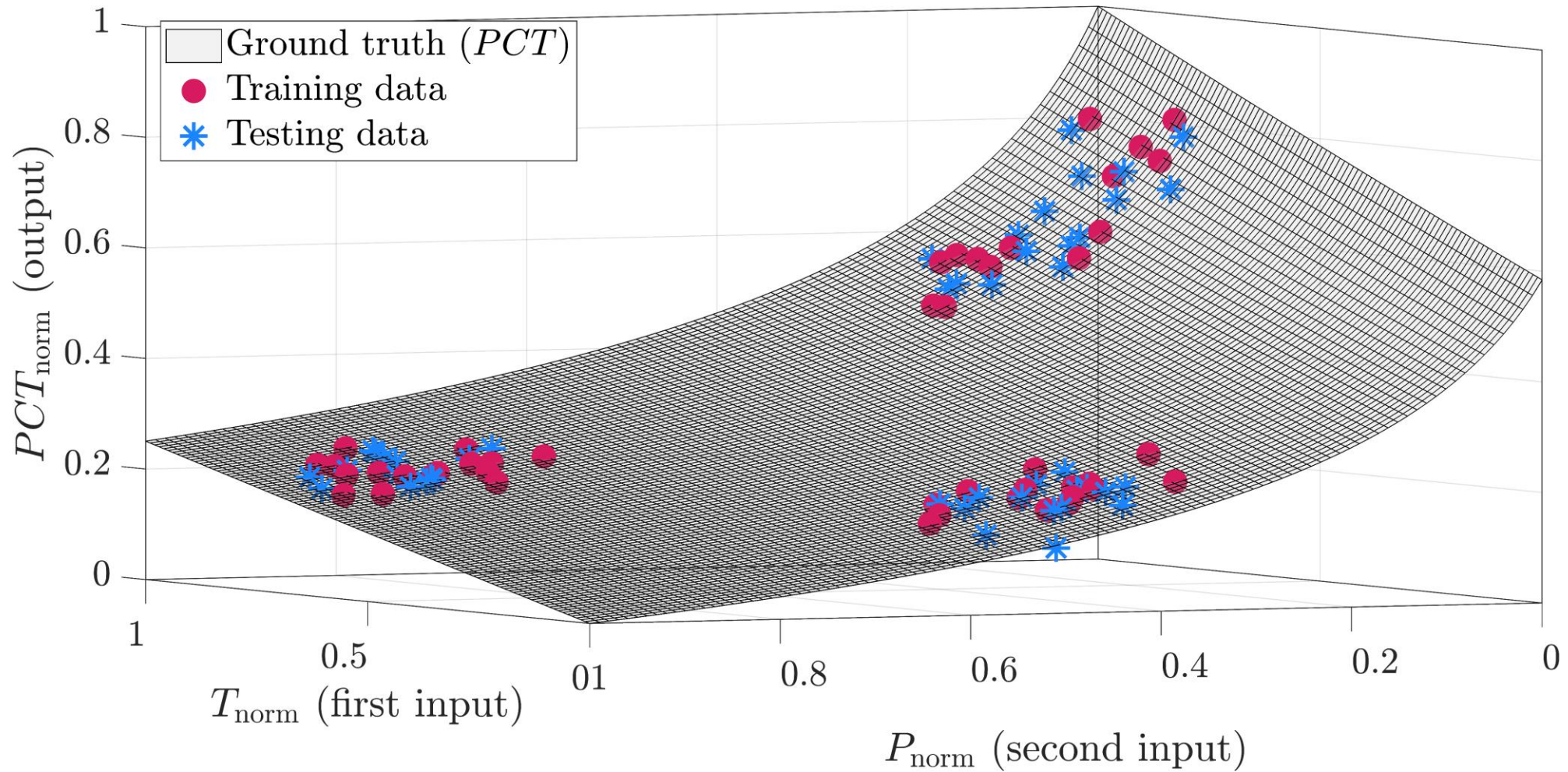
Case study: 2D \rightarrow 3D



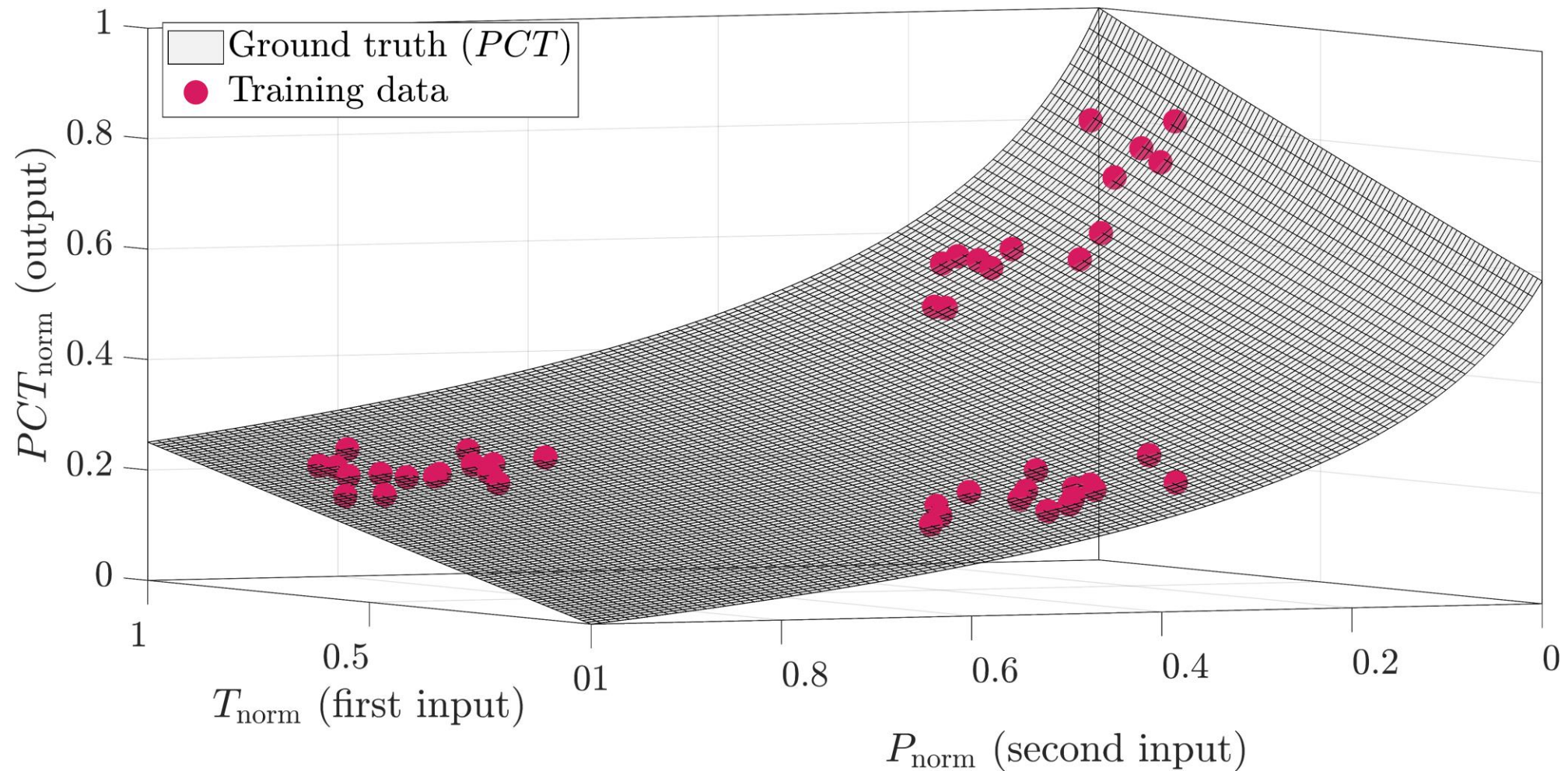


Approach	RMSE×10 ² (training)	RMSE×10 ² (testing)	CPU time [s]
SIS	4.1	3.5	0.1
MIS-SotA	0.9	1	4.3
MIS-con	0.9	1.1	4.1
MIS-con-lab (bar)	0.5	1.6	3,600.0
MIS-con-lab (bar,ht)	0.5	1.6	325.9
MIS-con-lab (gur)	0.4	0.5	2,284.0

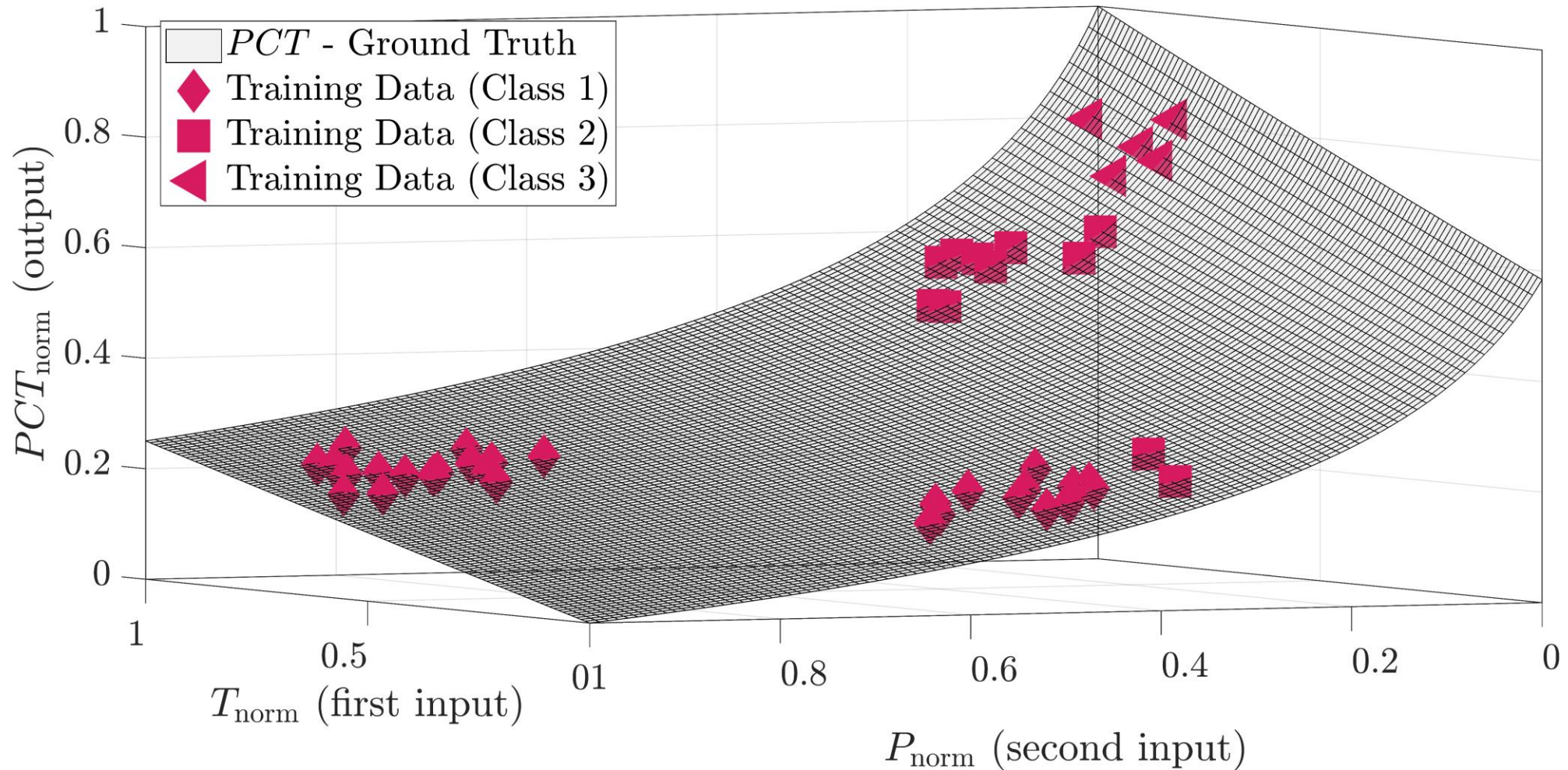
Windows 10.0.22621, x64-based PC, Intel(R) Core (TM) i7-8750H, 2.2GHz, 6 Core(s)



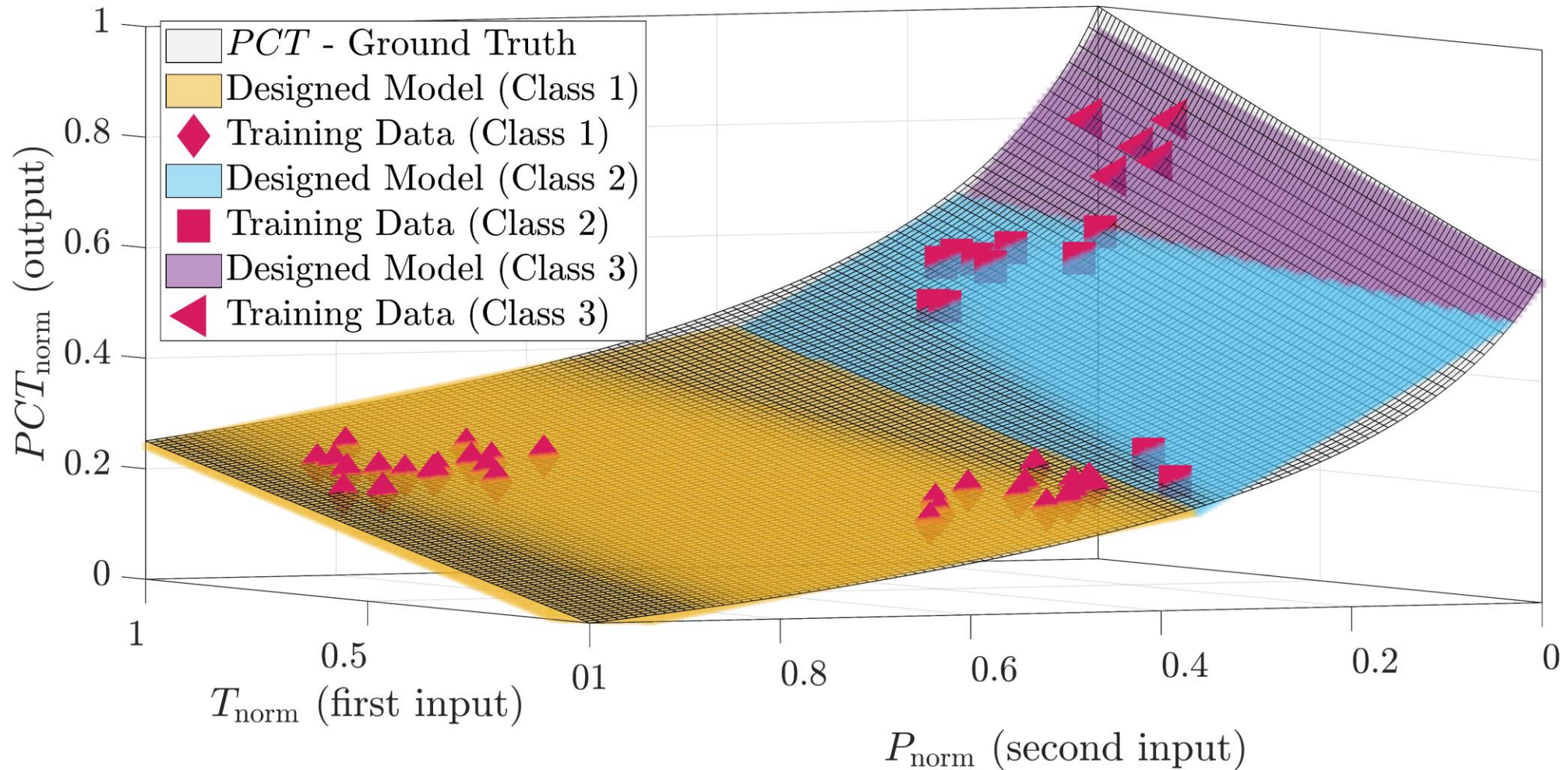
Approach: MIS-con-lab (gur)



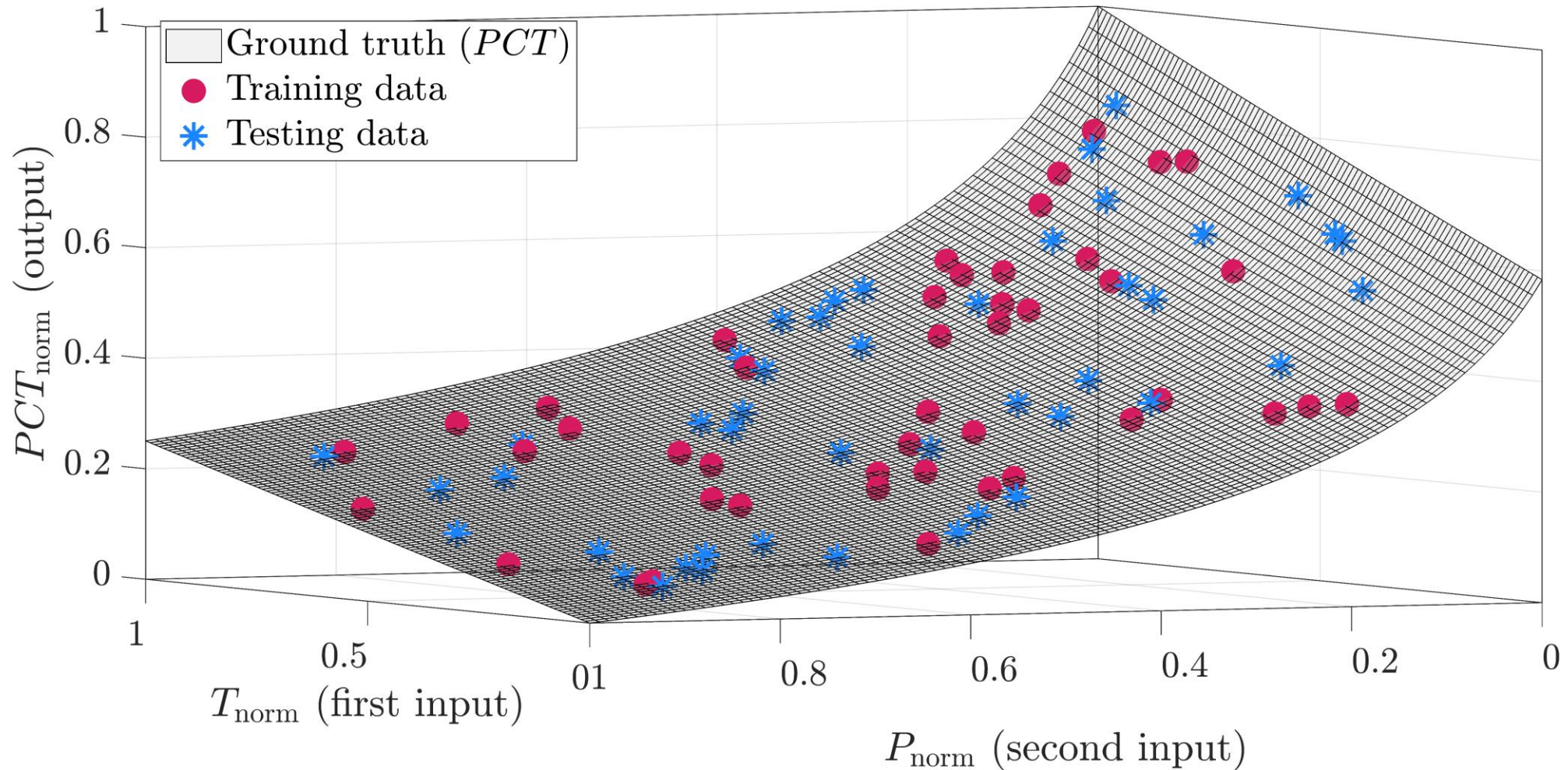
Approach: MIS-con-lab (gur)



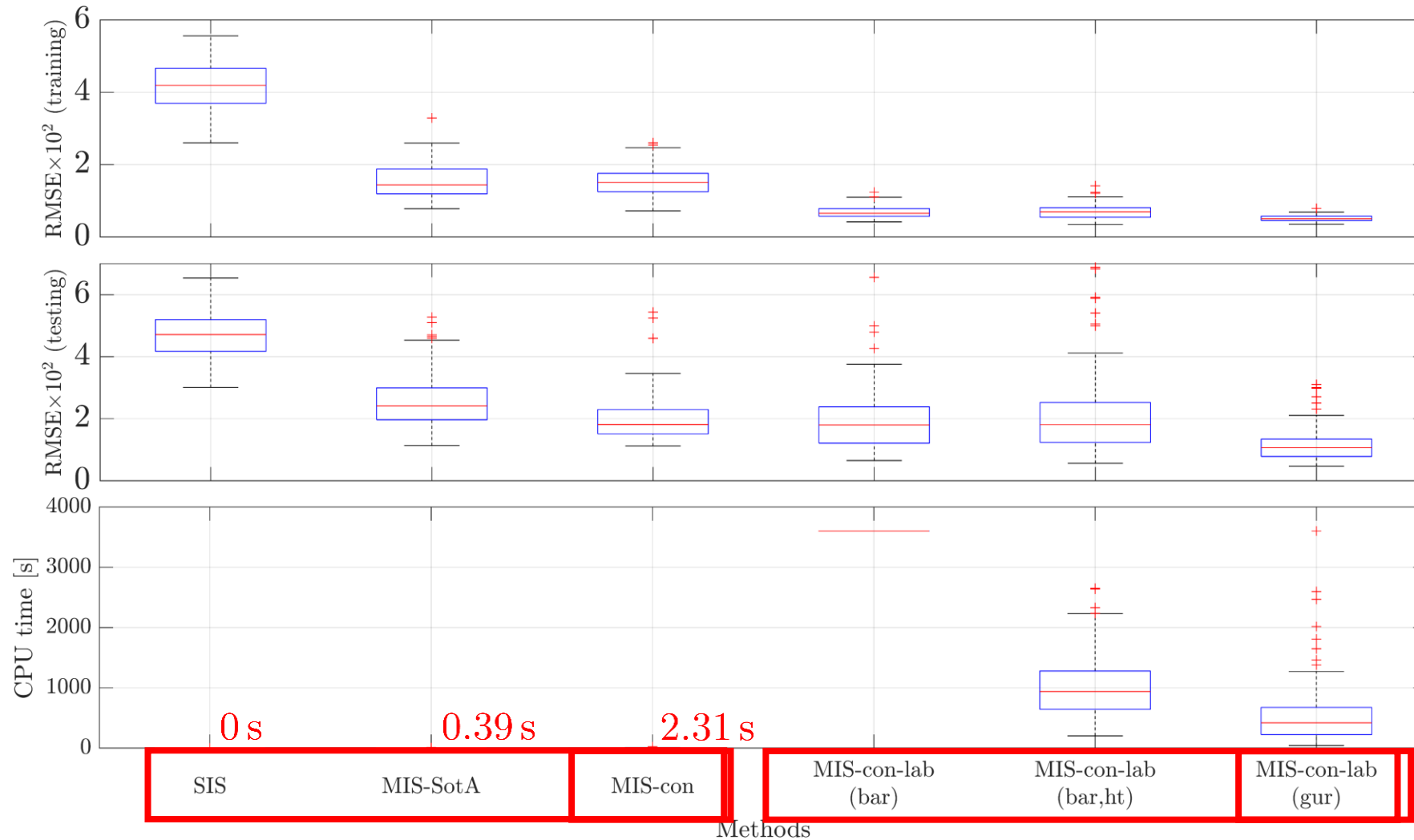
Approach: MIS-con-lab (gur)



Results: Uniformly Distributed Dataset

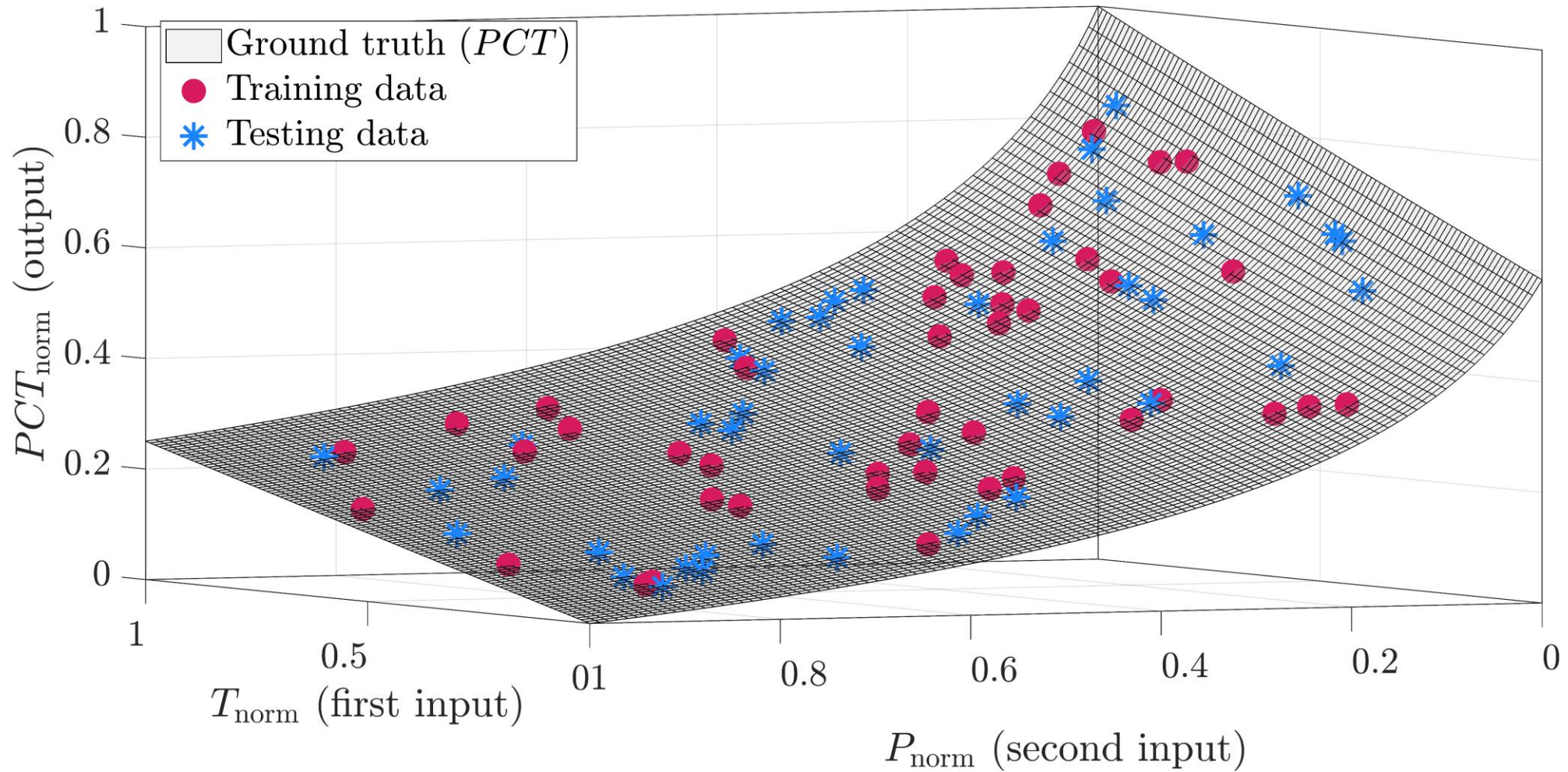


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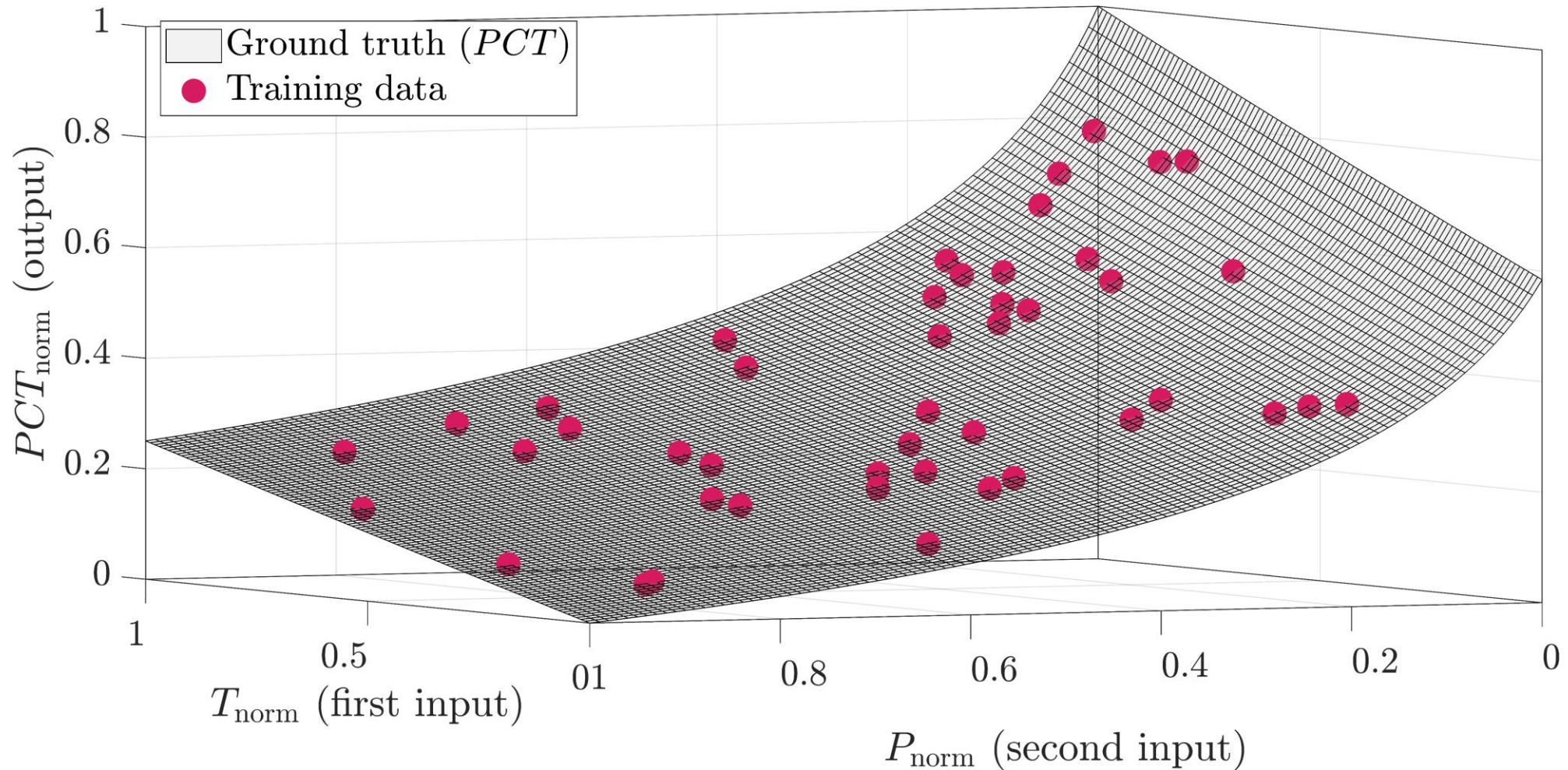
Windows 10.0.22621, x64-based PC, Intel(R) Core (TM) i7-8750H, 2.2GHz, 6 Core(s)

Results: Uniformly Distributed Dataset

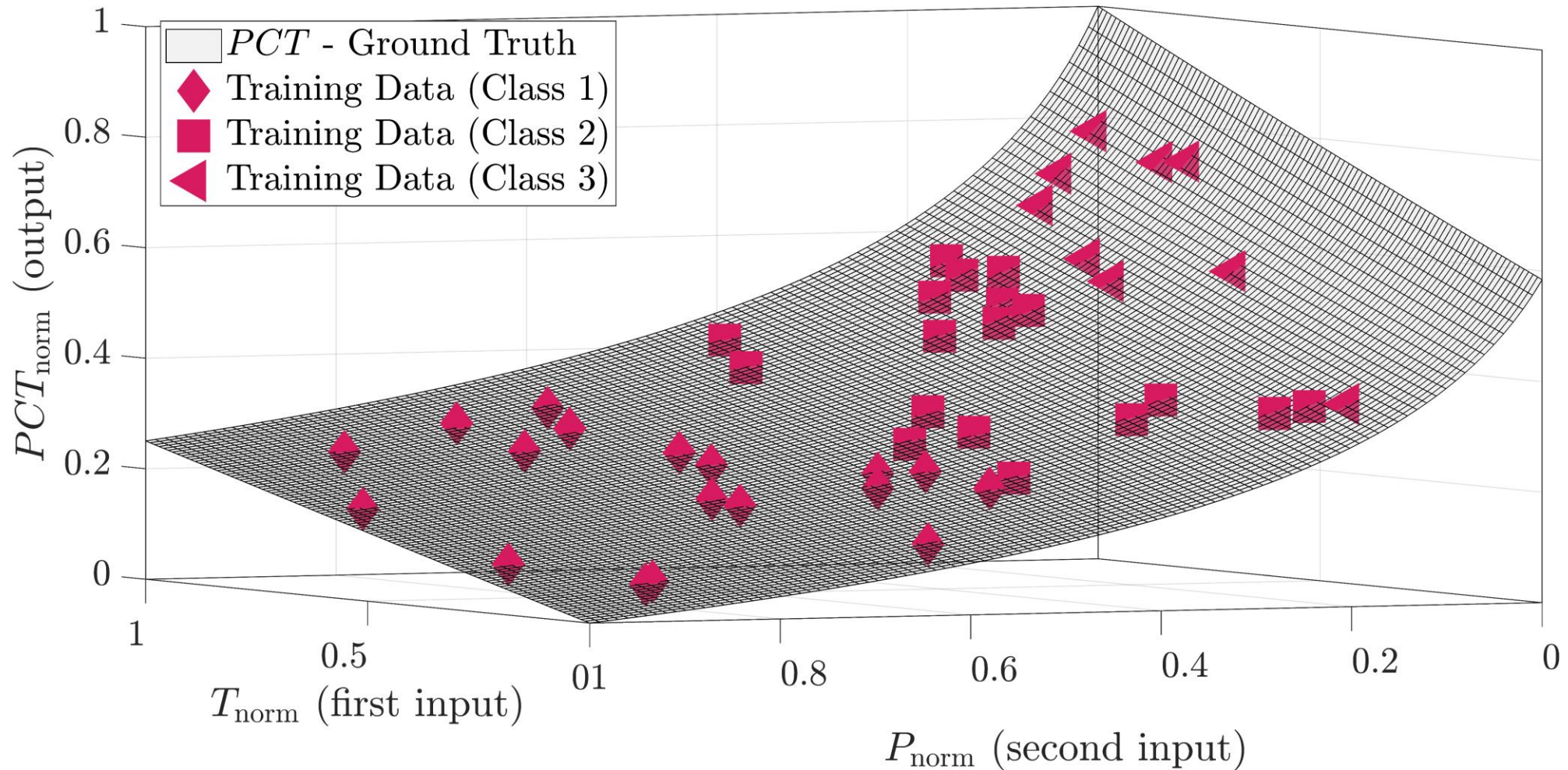


Results: Uniformly Distributed Dataset

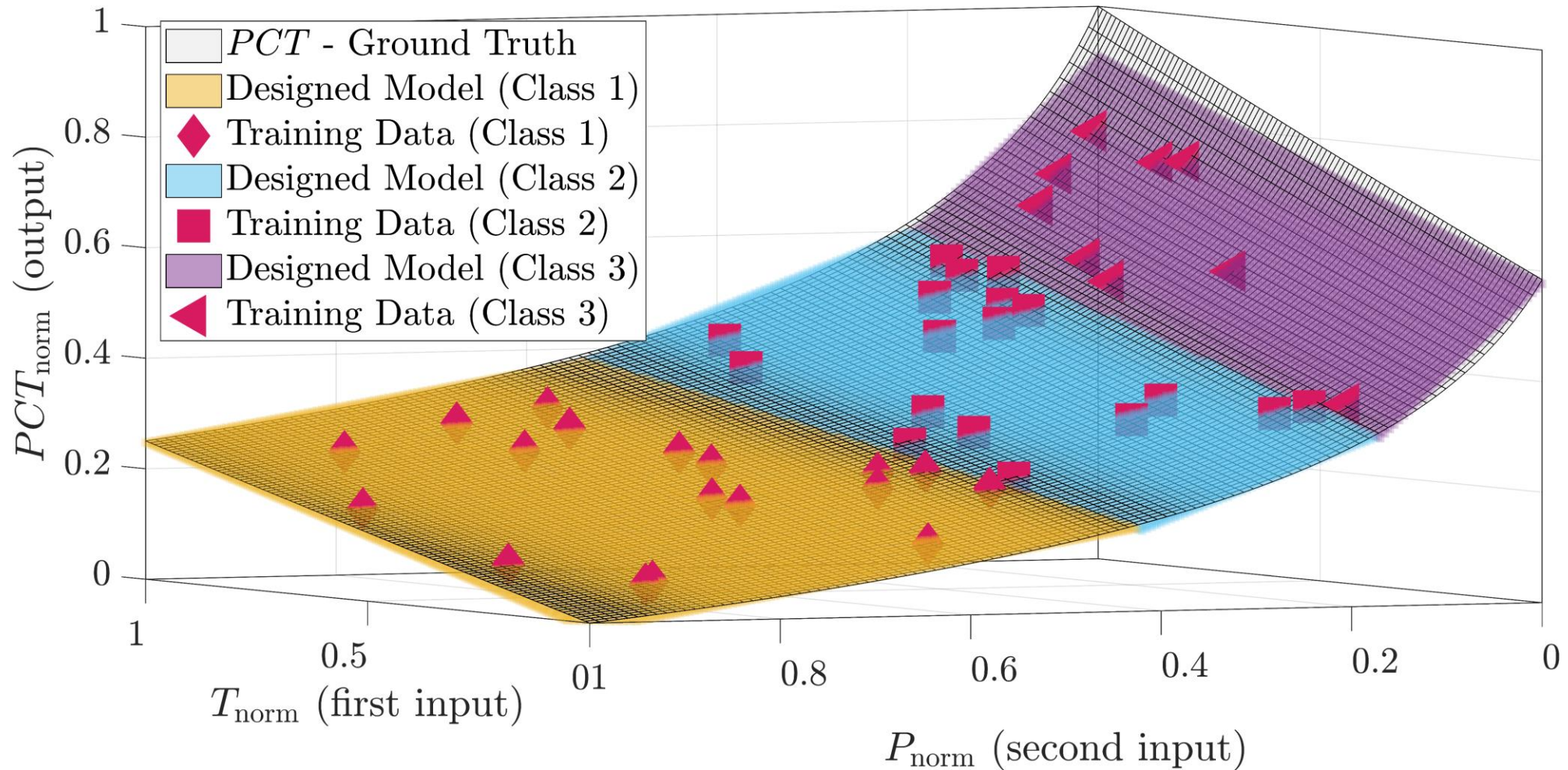
Approach: MIS-con-lab (gur)



Approach: MIS-con-lab (gur)



Approach: MIS-con-lab (gur)



- Based on the studied methodology, MIS-con-lab (gur) appears to be the most suitable approach.
- MIS-con offers the optimal balance between model accuracy, computational load, and model continuity.
- Optimising the data labels results in a significant computational load and variance in the results.



Future Work

- Consideration of advanced methods (e.g., LASSO) into MIS to allow different model structures.
- Incorporation of various approaches for data treatment to enhance data quality.

Acknowledgments



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VEGA 1/0691/21, VEGA 1/0297/22



European Commission under the grant no. 101079342 (Fostering Opportunities

Towards Slovak Excellence in Advanced Control for Smart Industries)